

Regulation for Medical Treatment by Monitoring and Control of Patient's Physiological Data

**Biophysical System Engineering
Graduate School of Health Sciences
Tokyo Medical and Dental University**

Prof. Dr. H.Wakamatsu

Overview of Studies

- **Management of Brain Temperature for Hypothermia**
- **Adaptive Control of Respiration**
- **Optimal Control of Intracranial Pressure**
- **Monitoring and Determination of Physiological State**

Development of Automatic Control System of Hypothermia

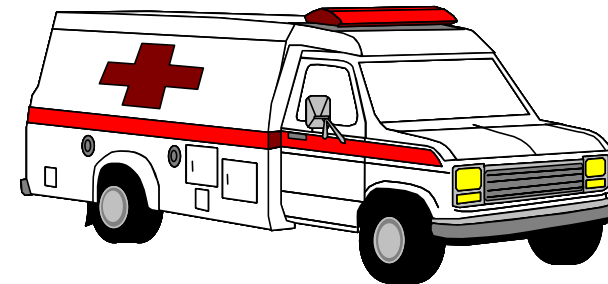
- Accurate Management of Brain Temperature
- Optimal and Fuzzy Control Processes
- Release from Heavy Loads
Physical, Psychological & Economic Burdens
- Improve Medical Condition and Treatment

Based on “System Engineering”

Simulation \Rightarrow Experiment

Situation

What's matter with him?
It's awful. It's terrible.
Hurry up! Bring him to hospital!

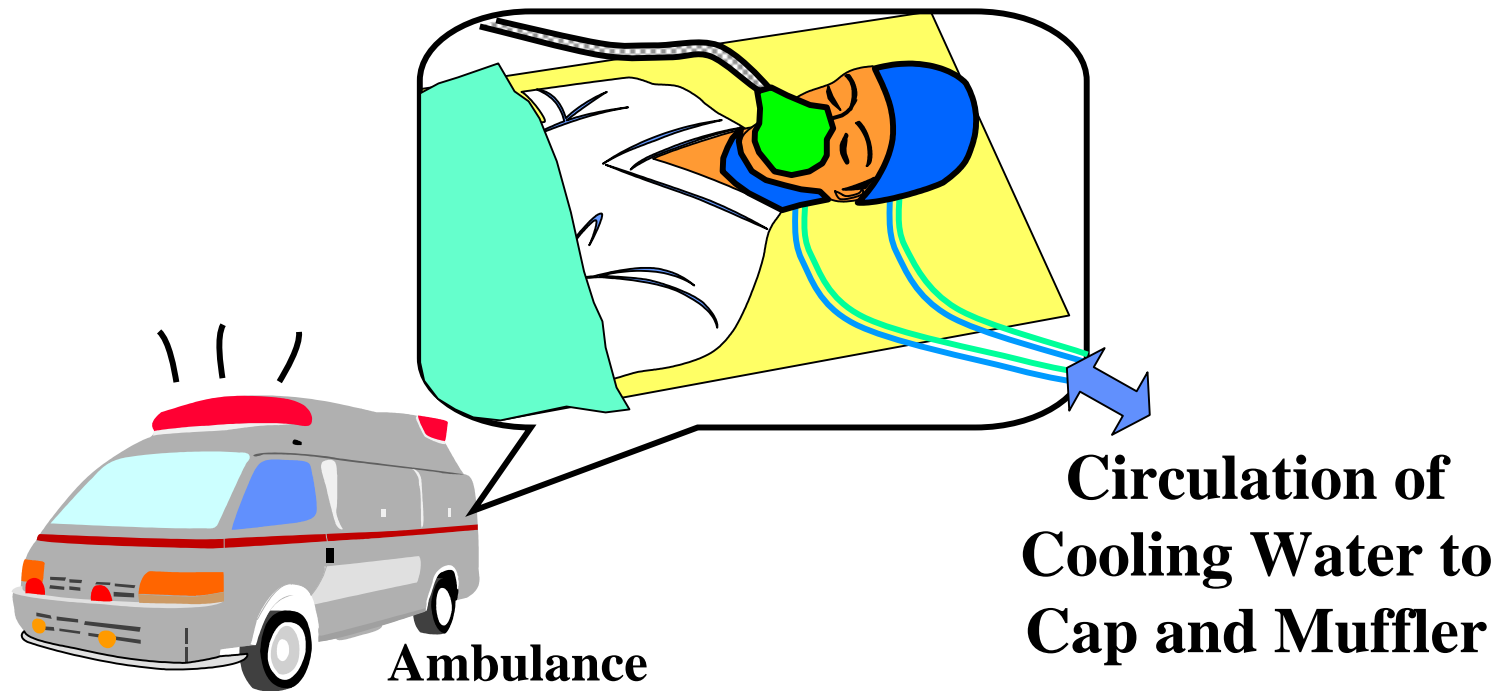


Ambulance

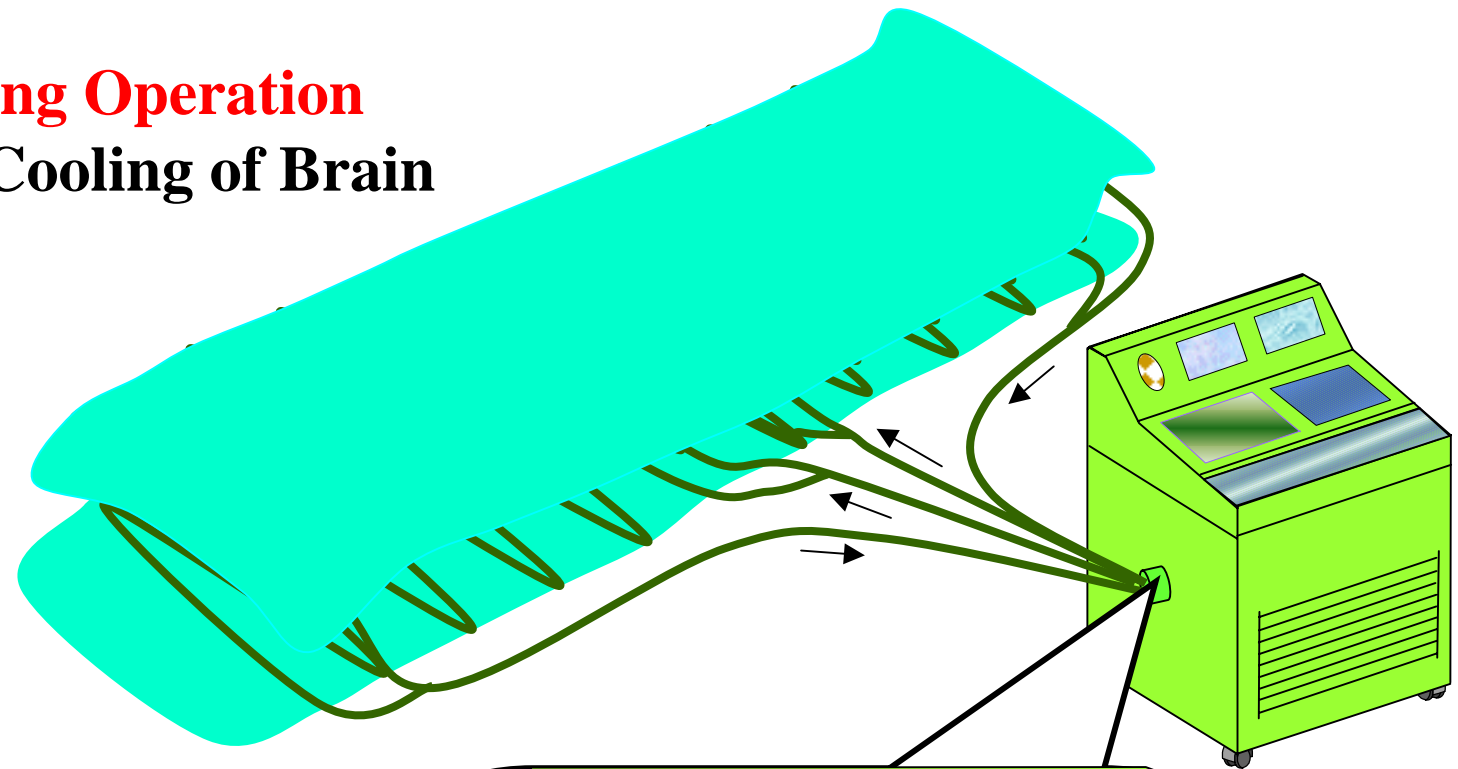


Traffic Accident

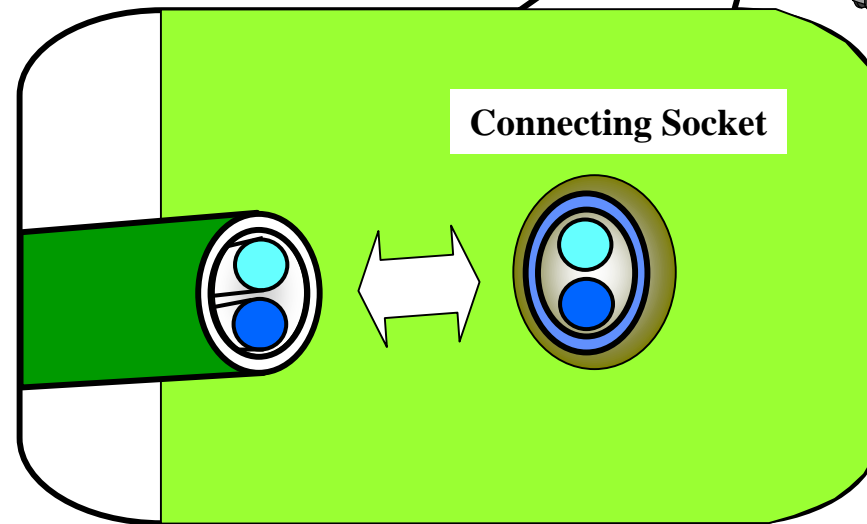
**Set Quick Cooling Brain Temperature
By Using Cooling Cap and Muffler**

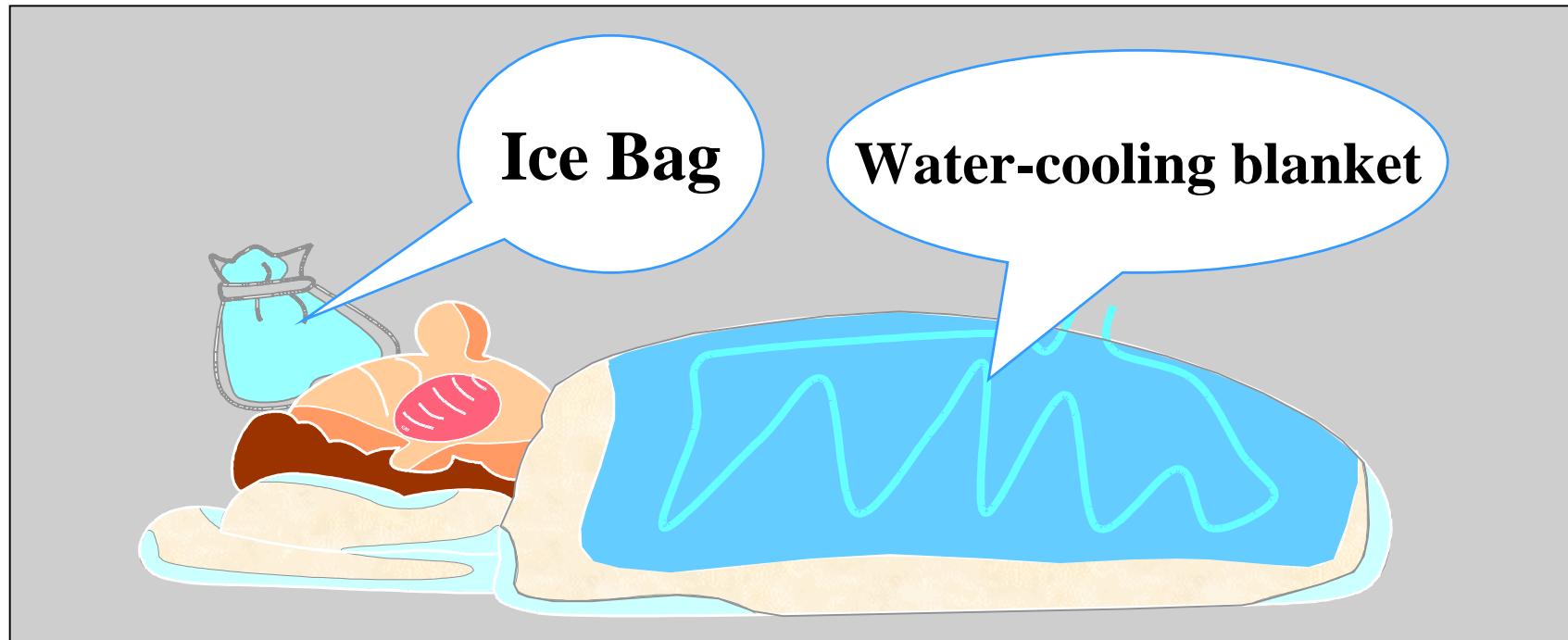


Simple Connecting Operation
Quickly Begins Cooling of Brain



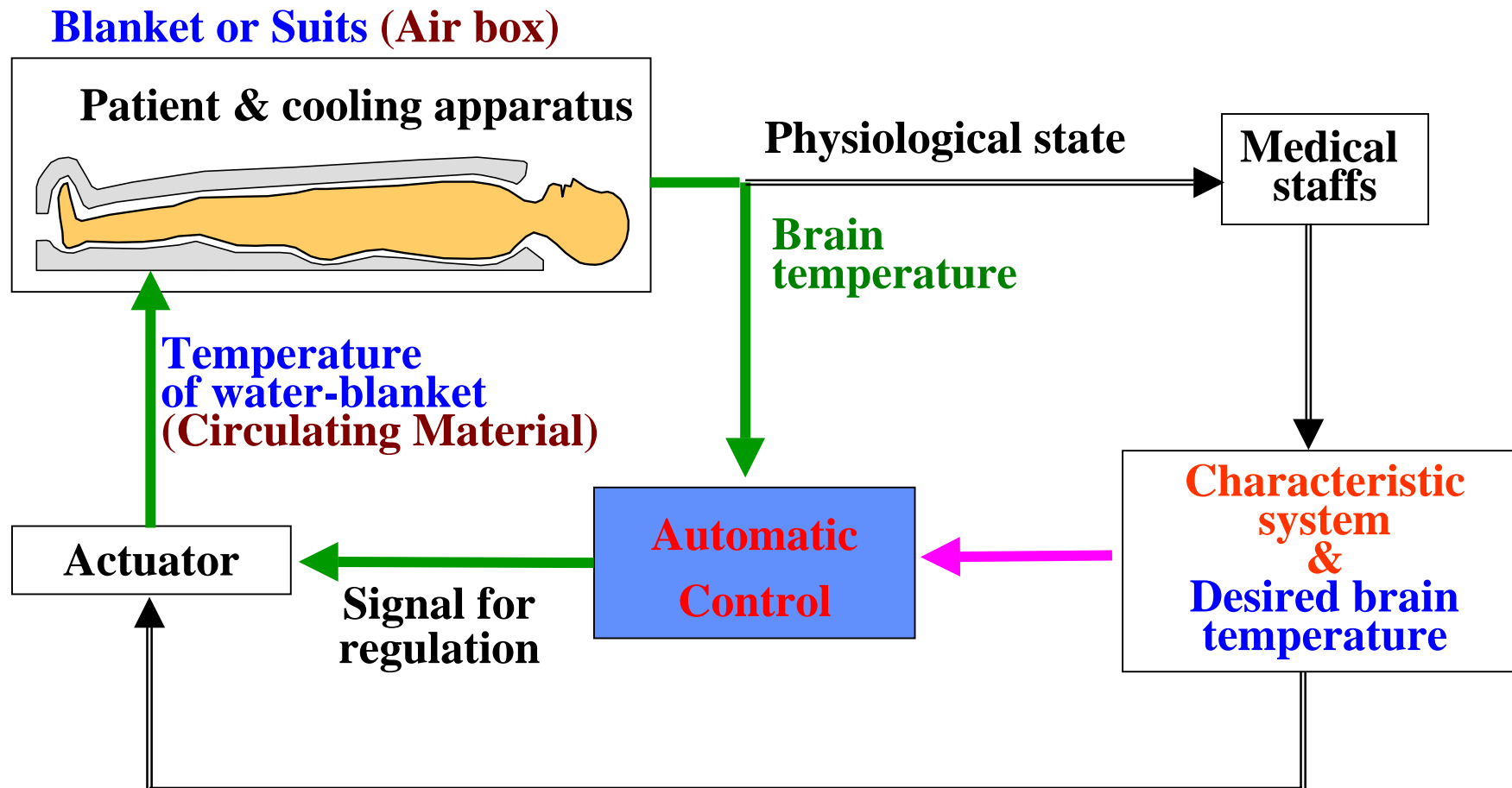
To Cooling Branket





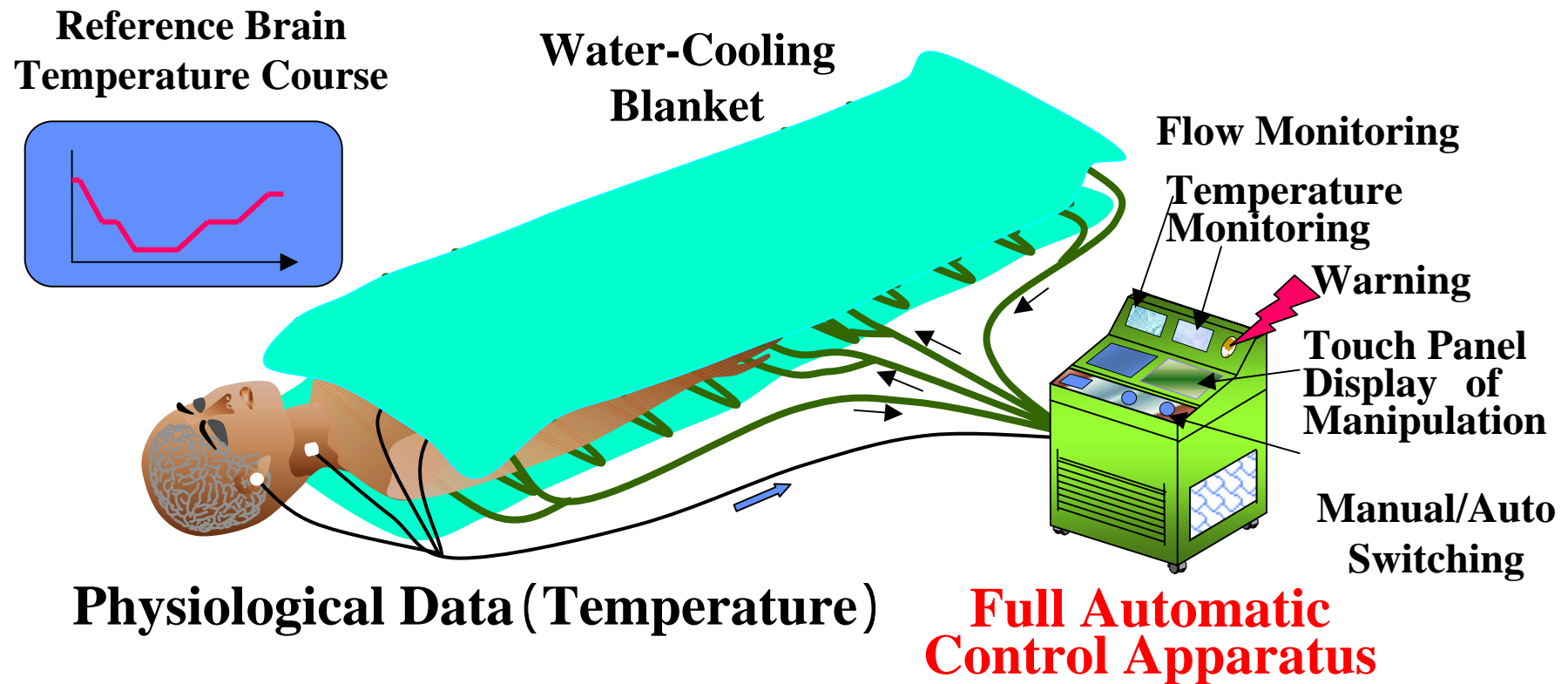
- **Whole Body Cooling is Effective**
- **Head Cooling as Assistance**

Automatic Control of Brain Temperature

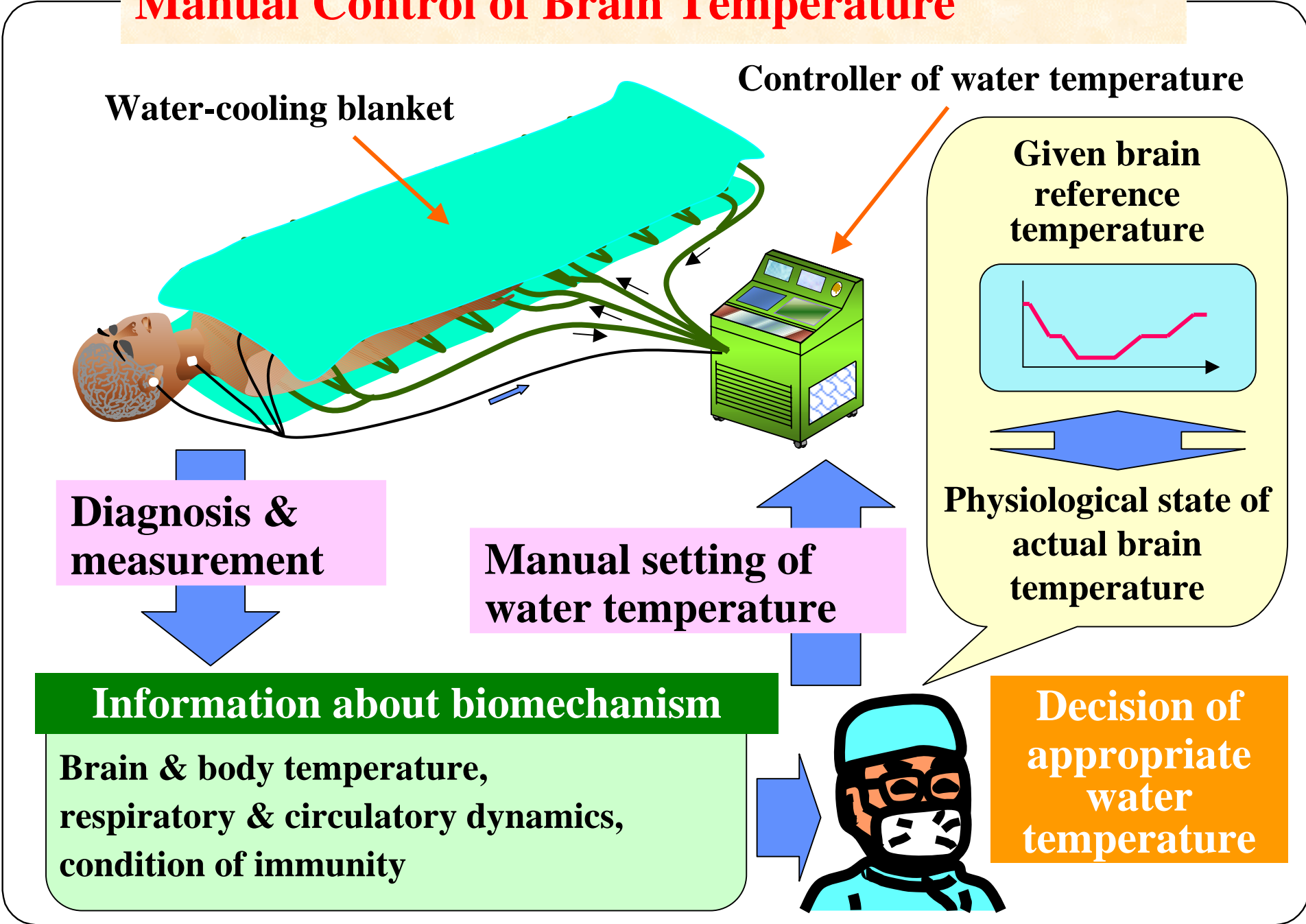


Manual regulation

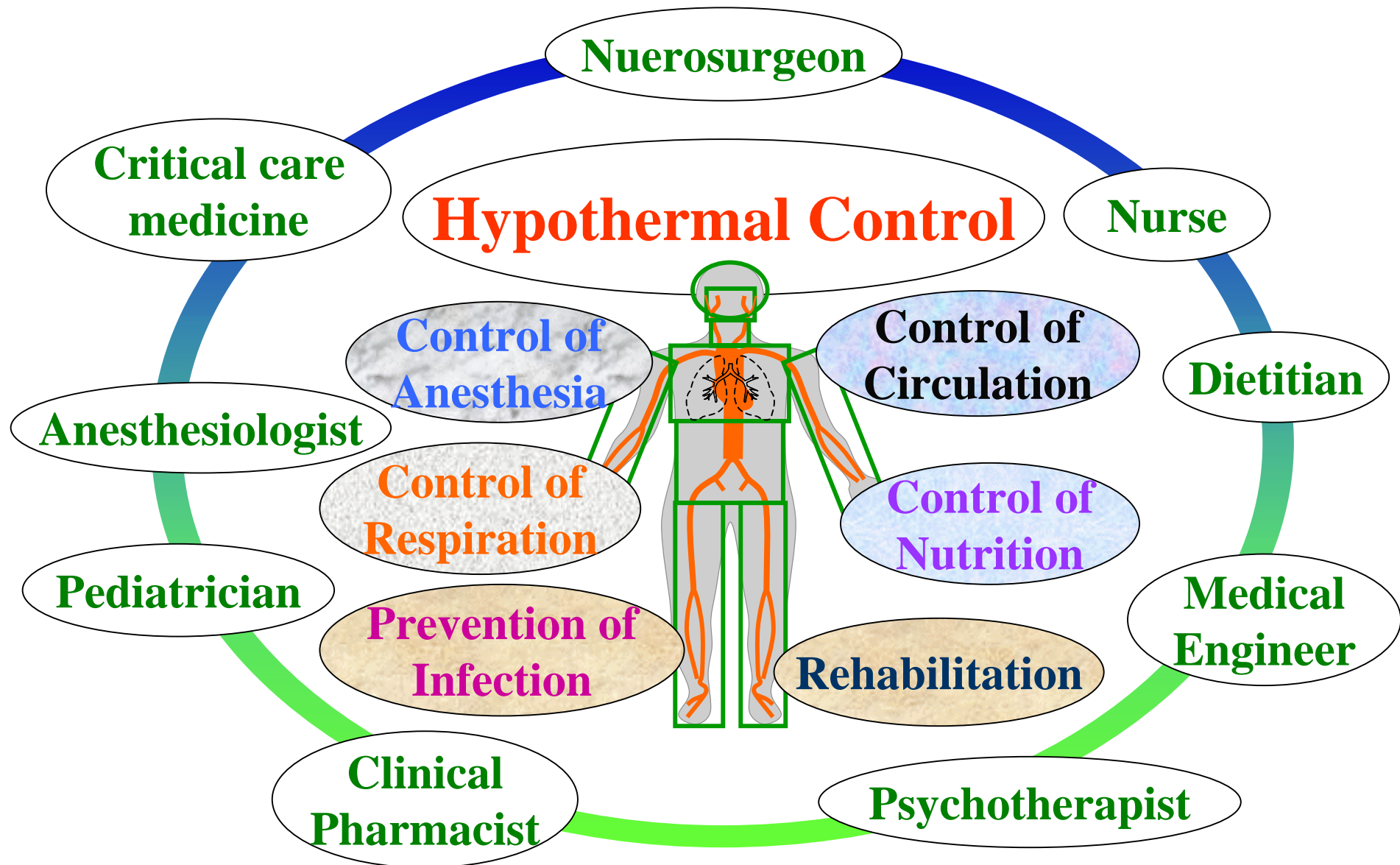
Automatic Control Apparatus of Brain Temperature



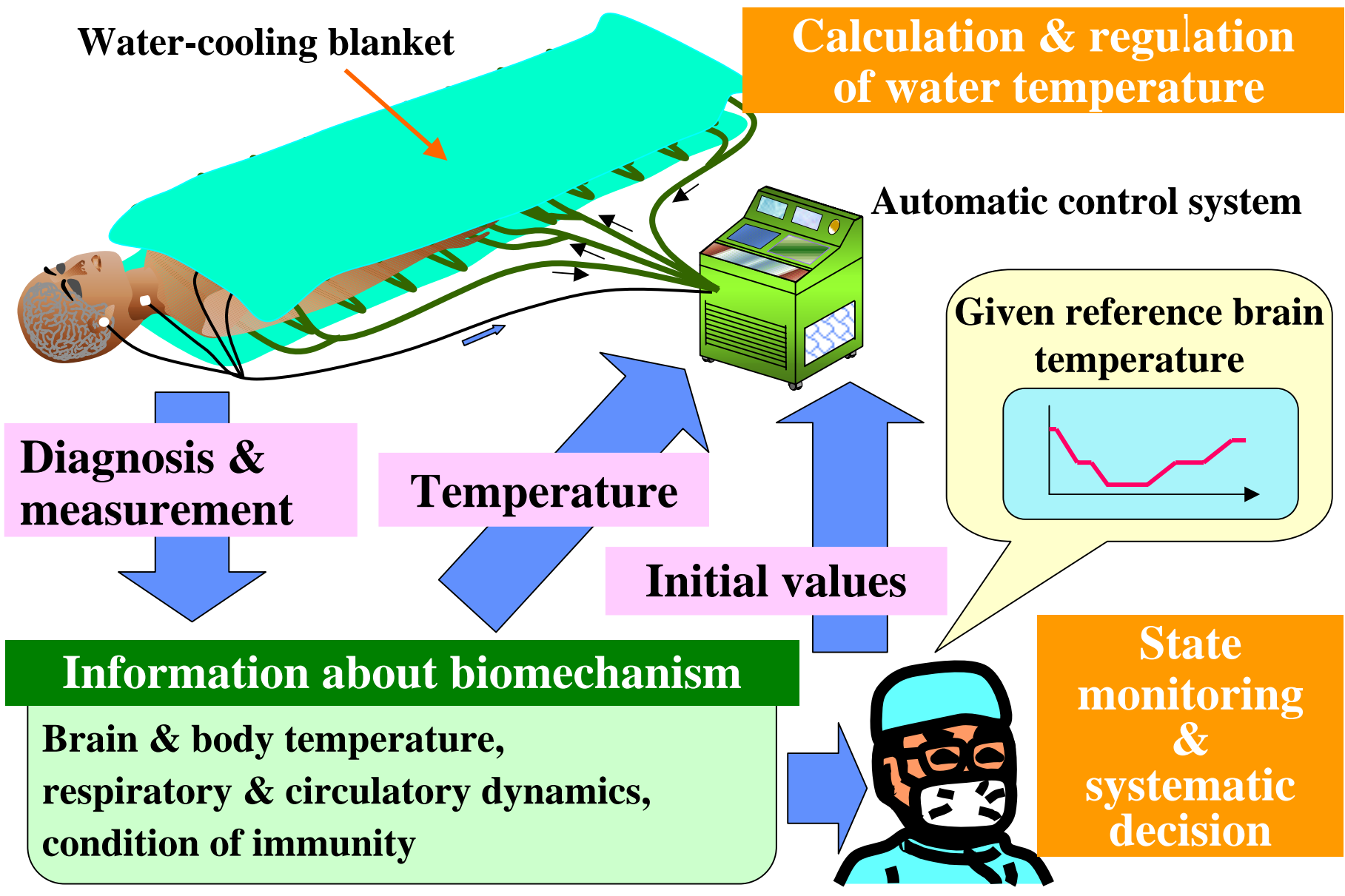
Manual Control of Brain Temperature



Hypothermia Treatment in ICU



Automatic Control of Brain Temperature



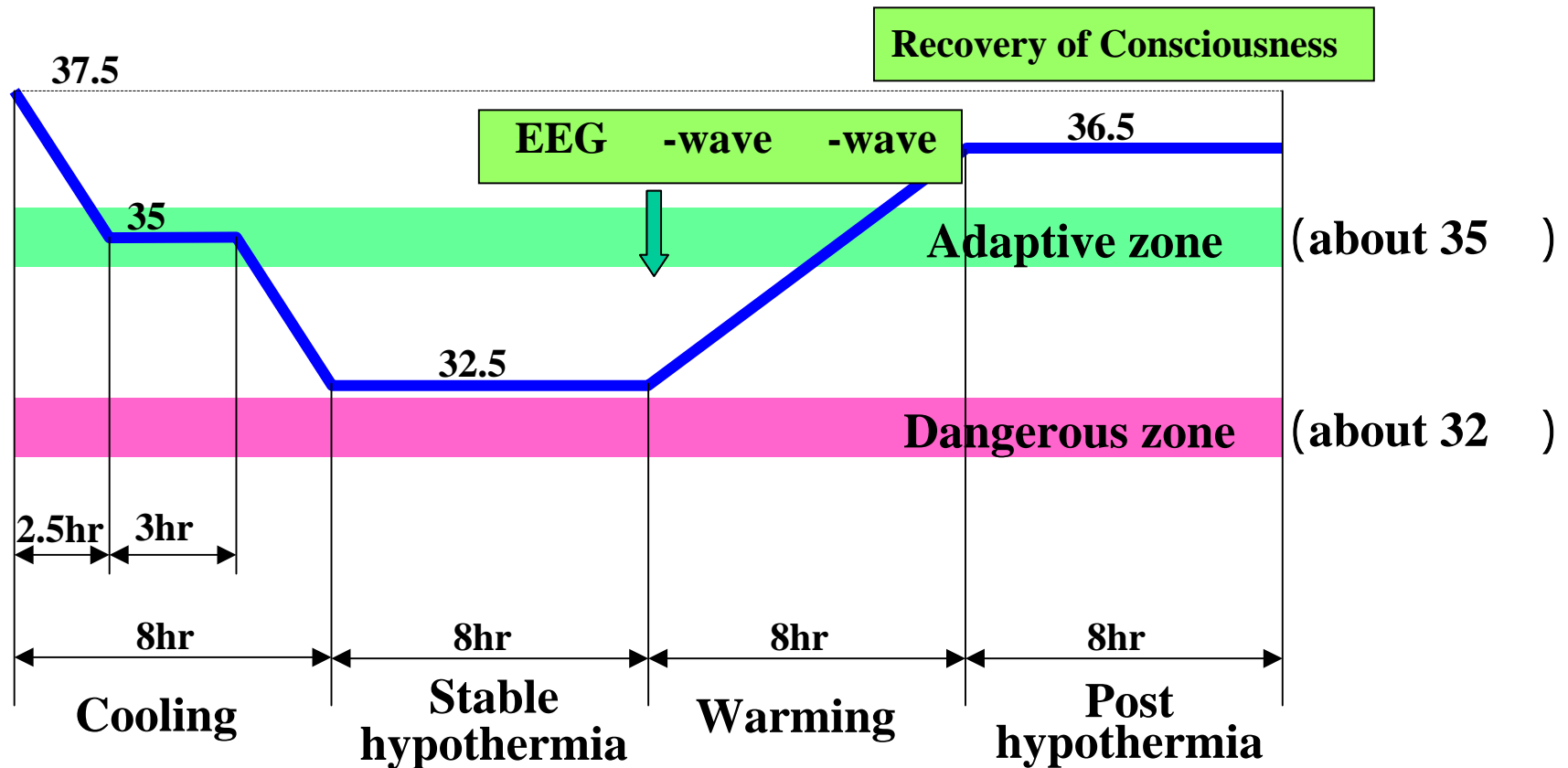
Control of Brain Temperature by Water-Cooling System



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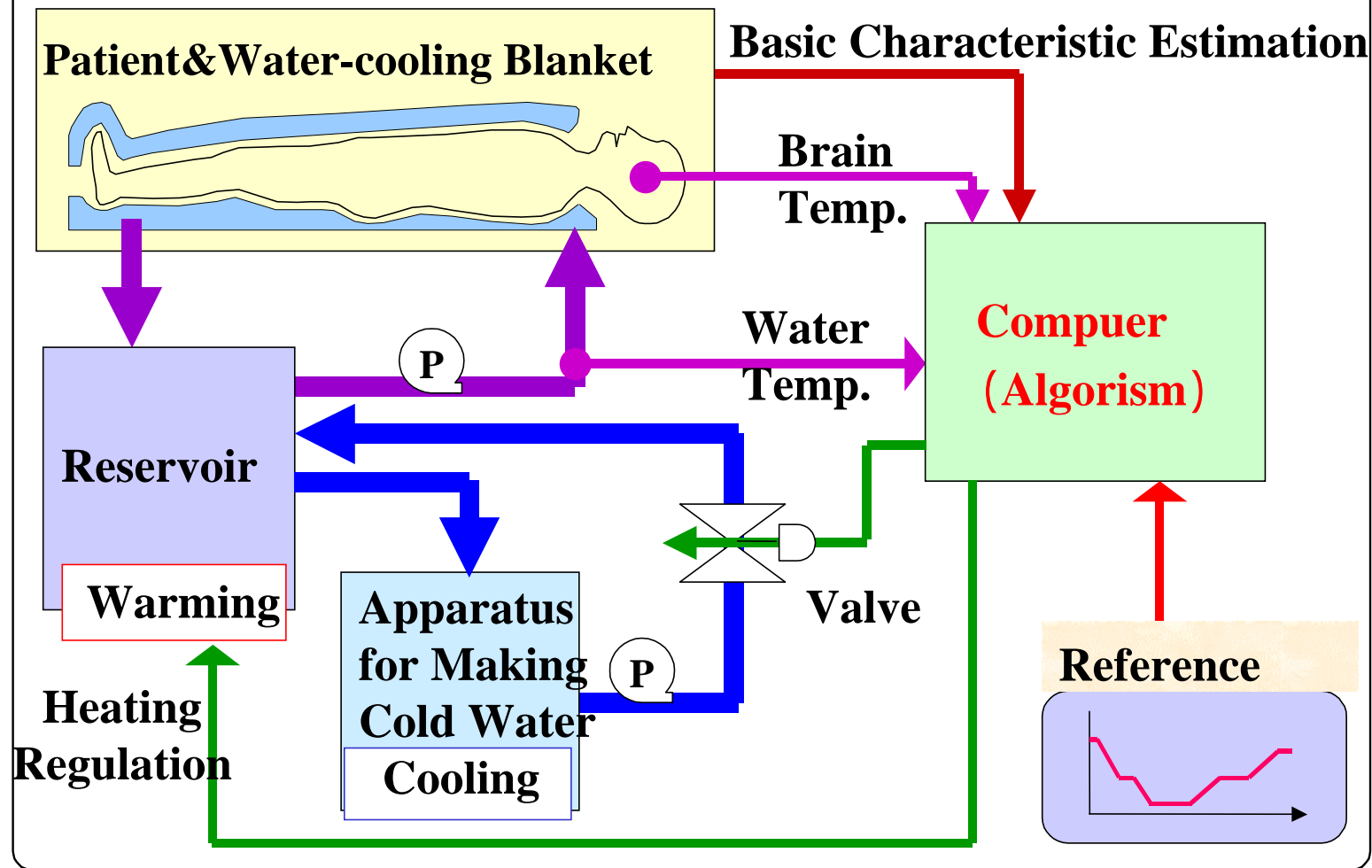
H.Wakamatsu, T.Utsuki, T.Wakatsuki

Schematic Desired Brain Temperature

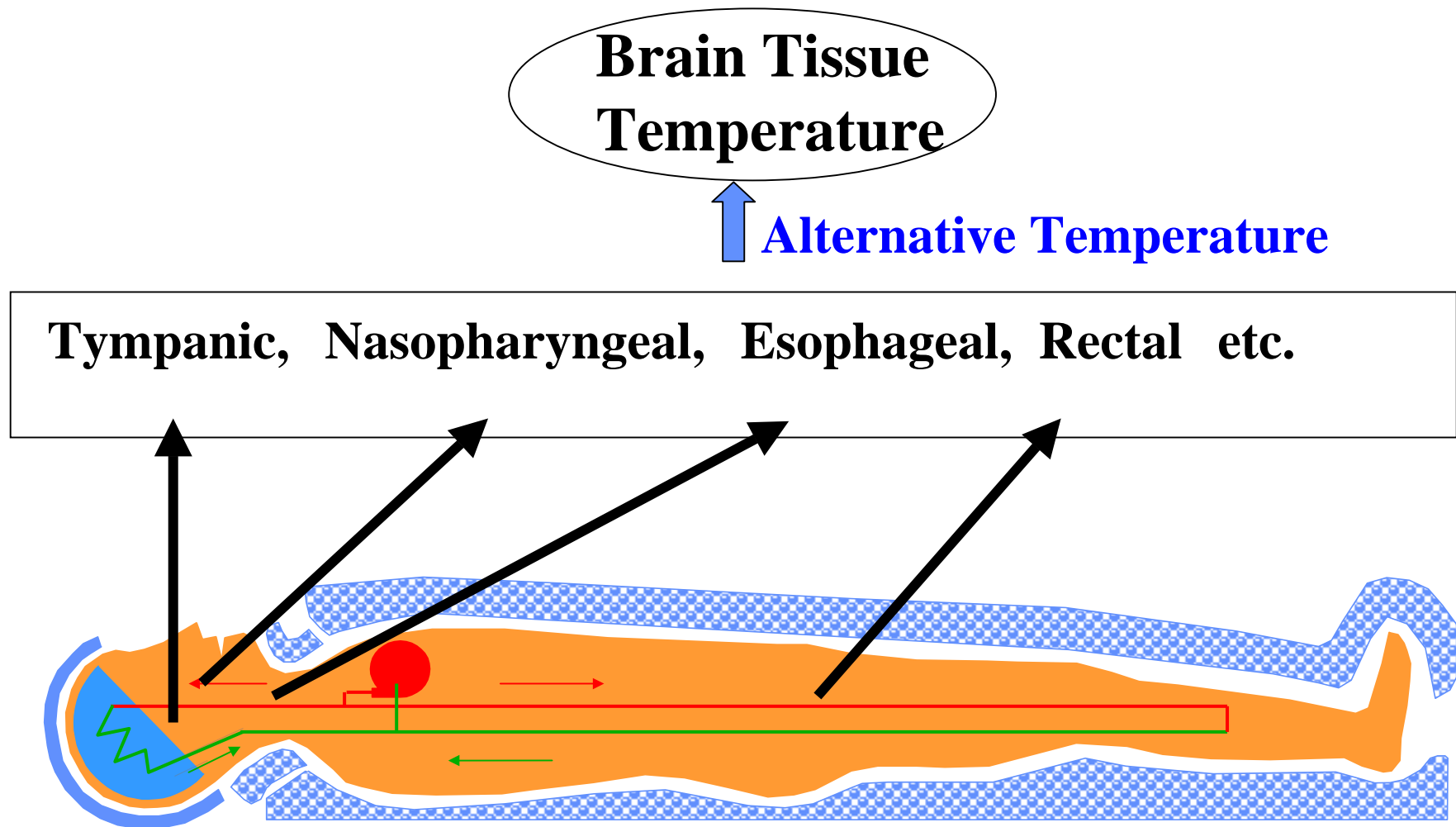


Step-by-step Management of Body Temperature

Automatic Controller of Brain Temperature



Measurement of Temperature in Hypothermia

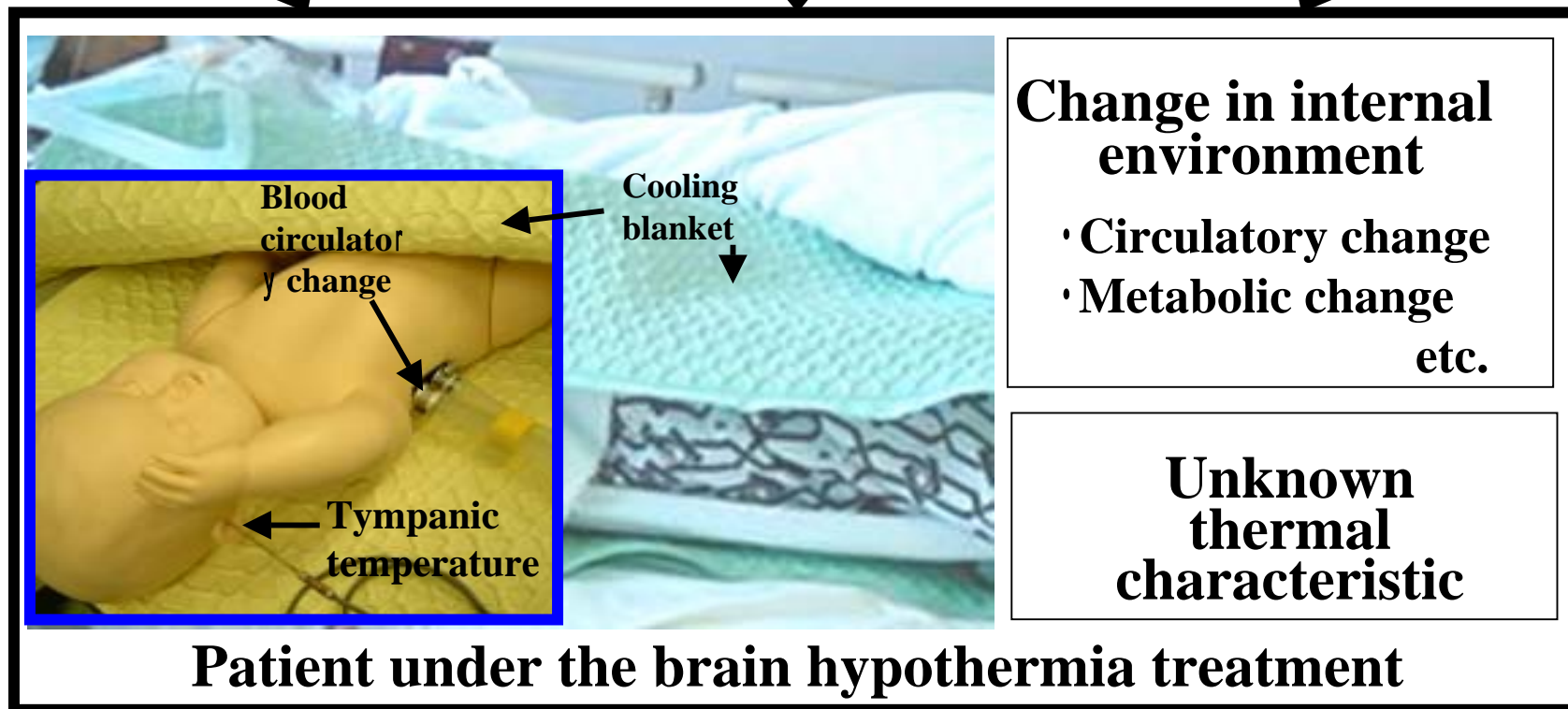


Concept of Adaptive Control Engineering

Different regulation

Various kinds of medical treatment

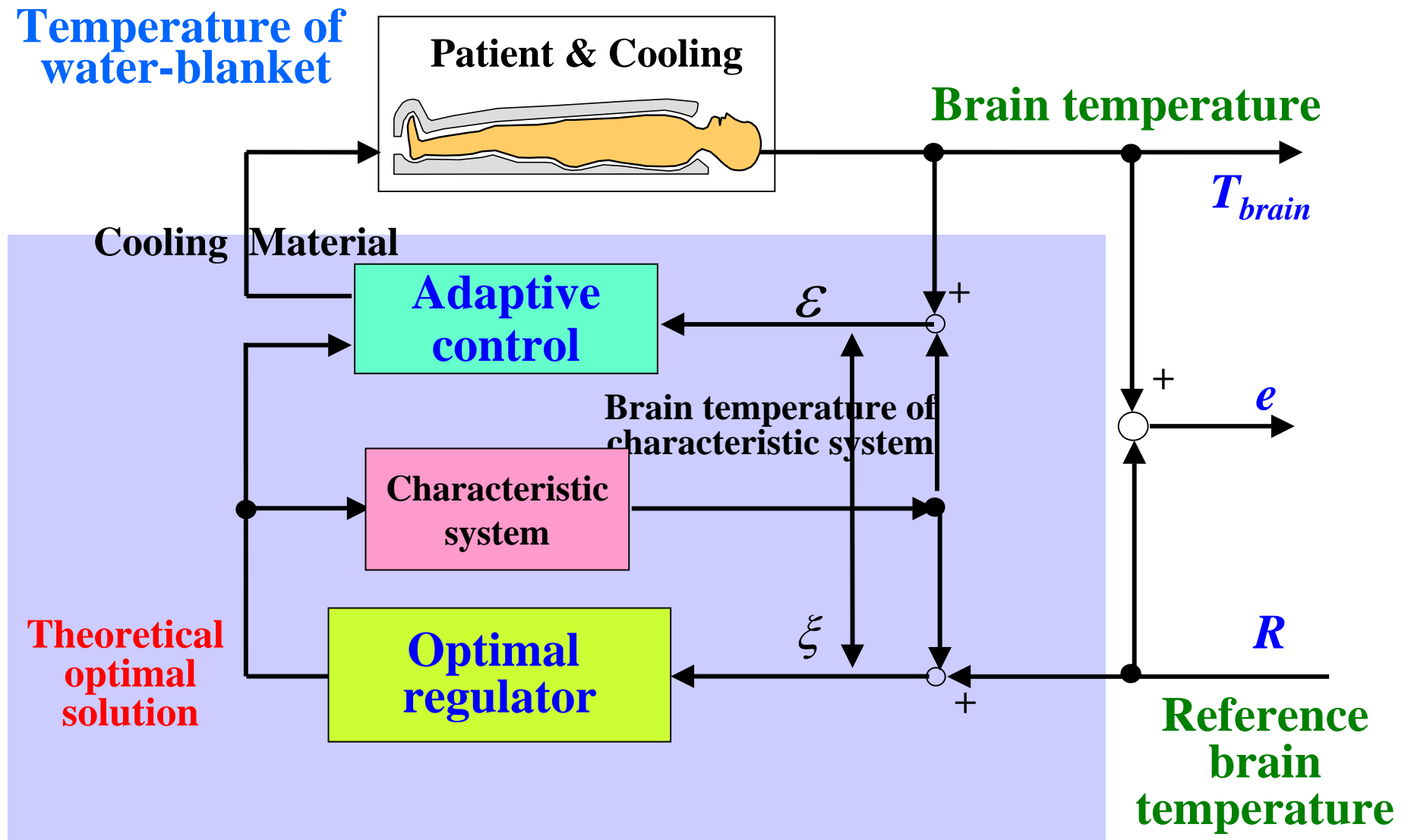
Change in external environment



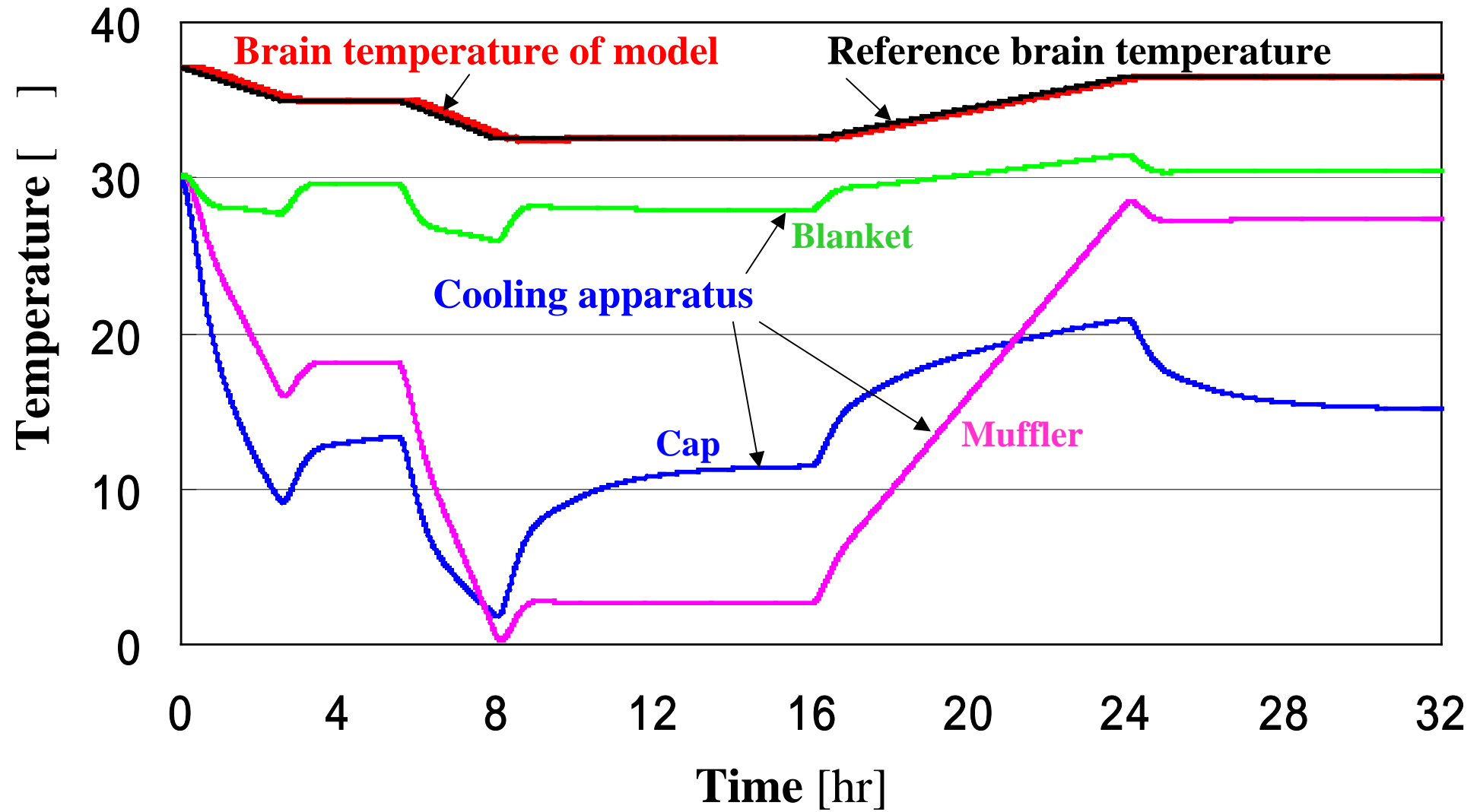
Adaptive control

Realization of desired brain temperature

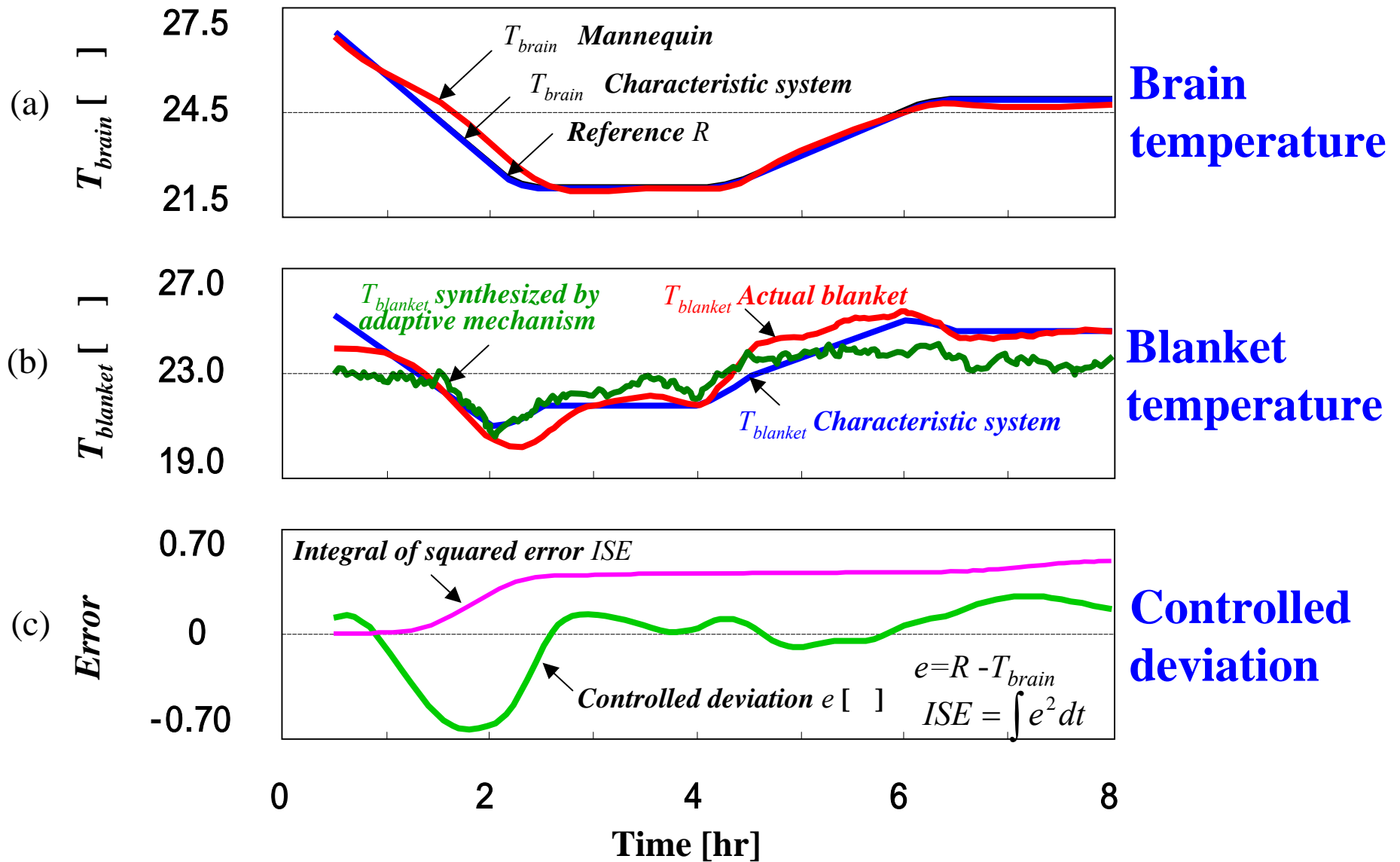
Optimal · Adaptive Control



Control using Solution by Optimal Calculation



Experimental Result

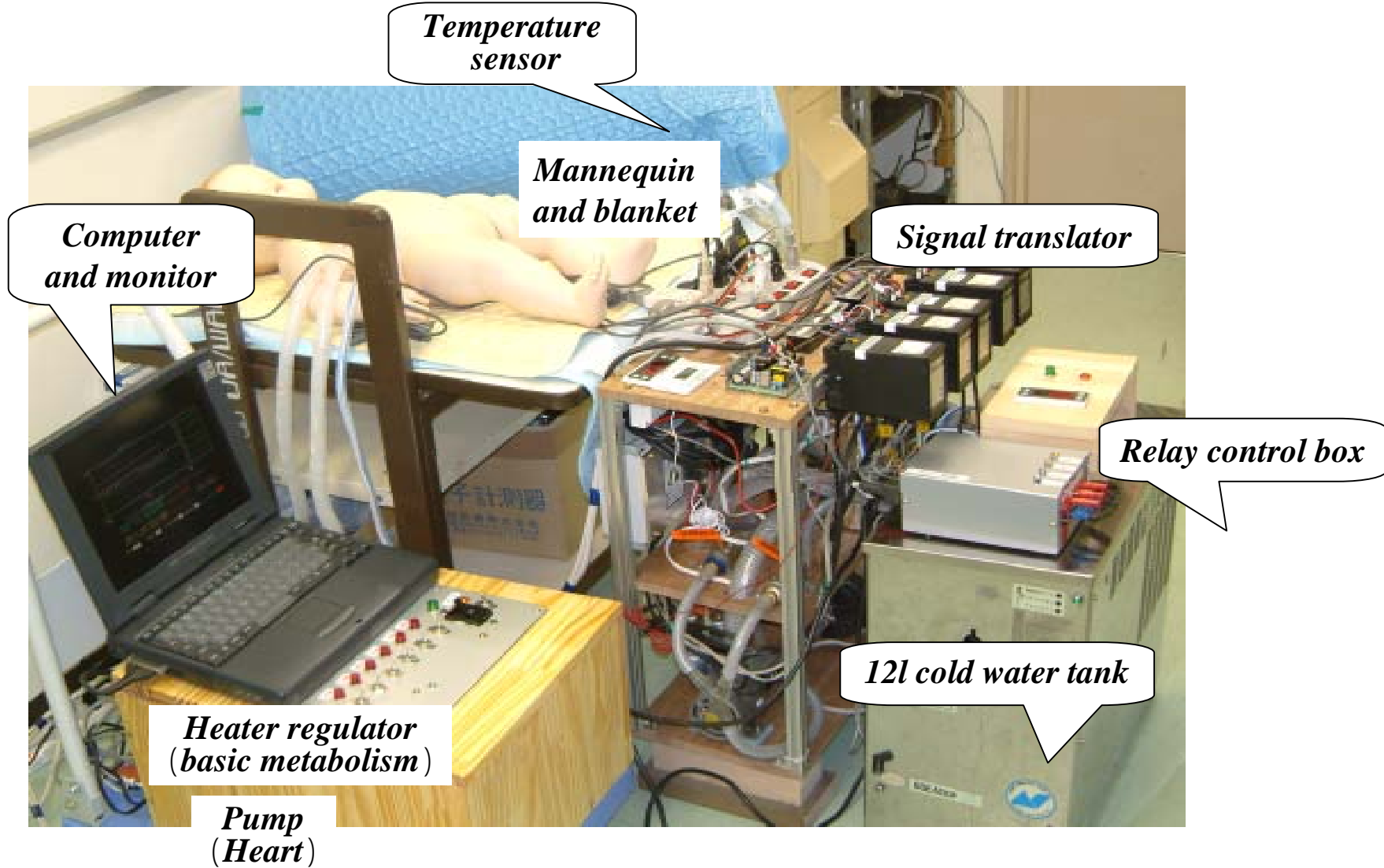


Brain Hypothermia Treatment Using Thermal Mannequin



Mannequin controlled by water circulation (blood flow) and heater (metabolic heat)

Overview of Experimental Equipment (1)

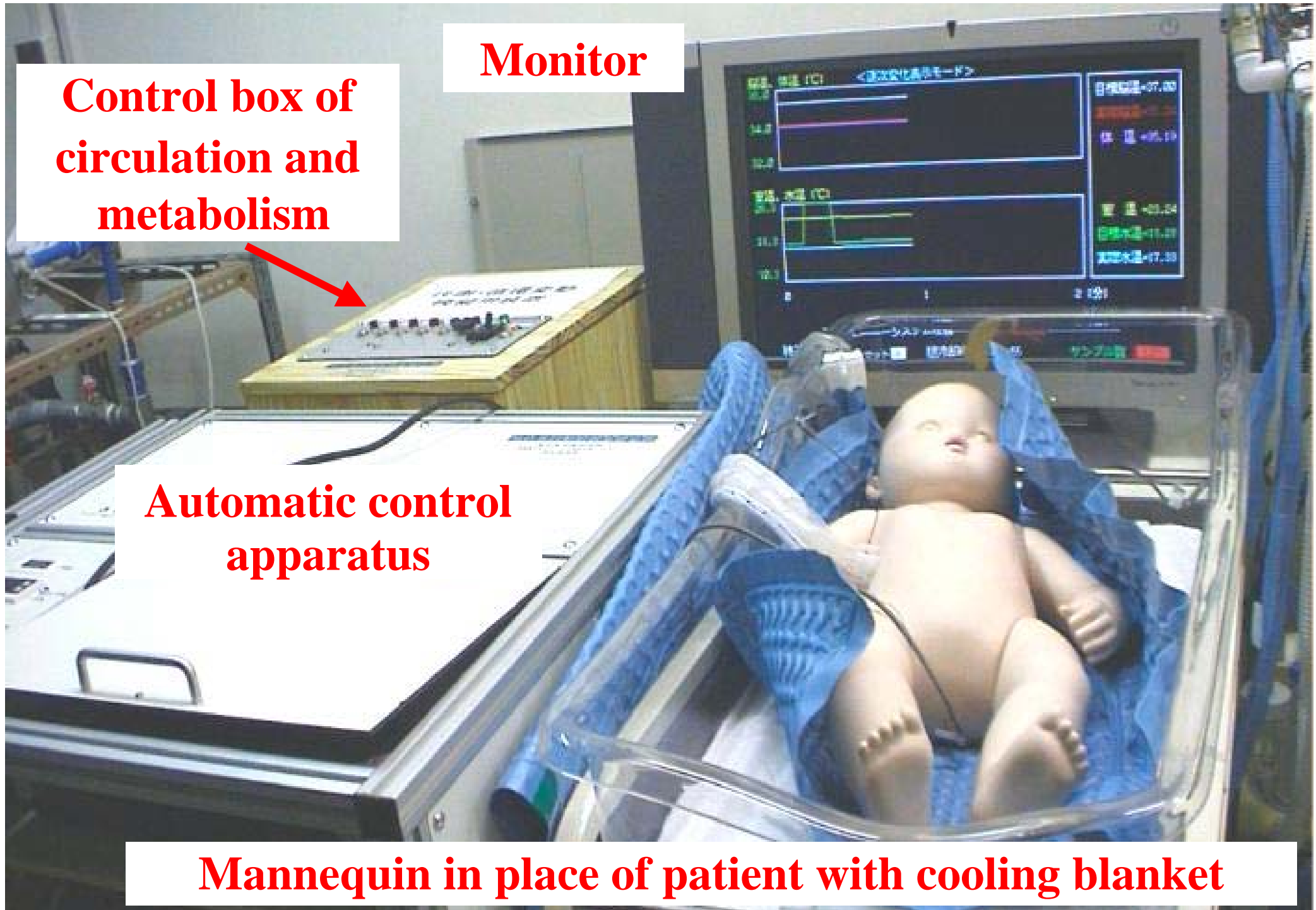


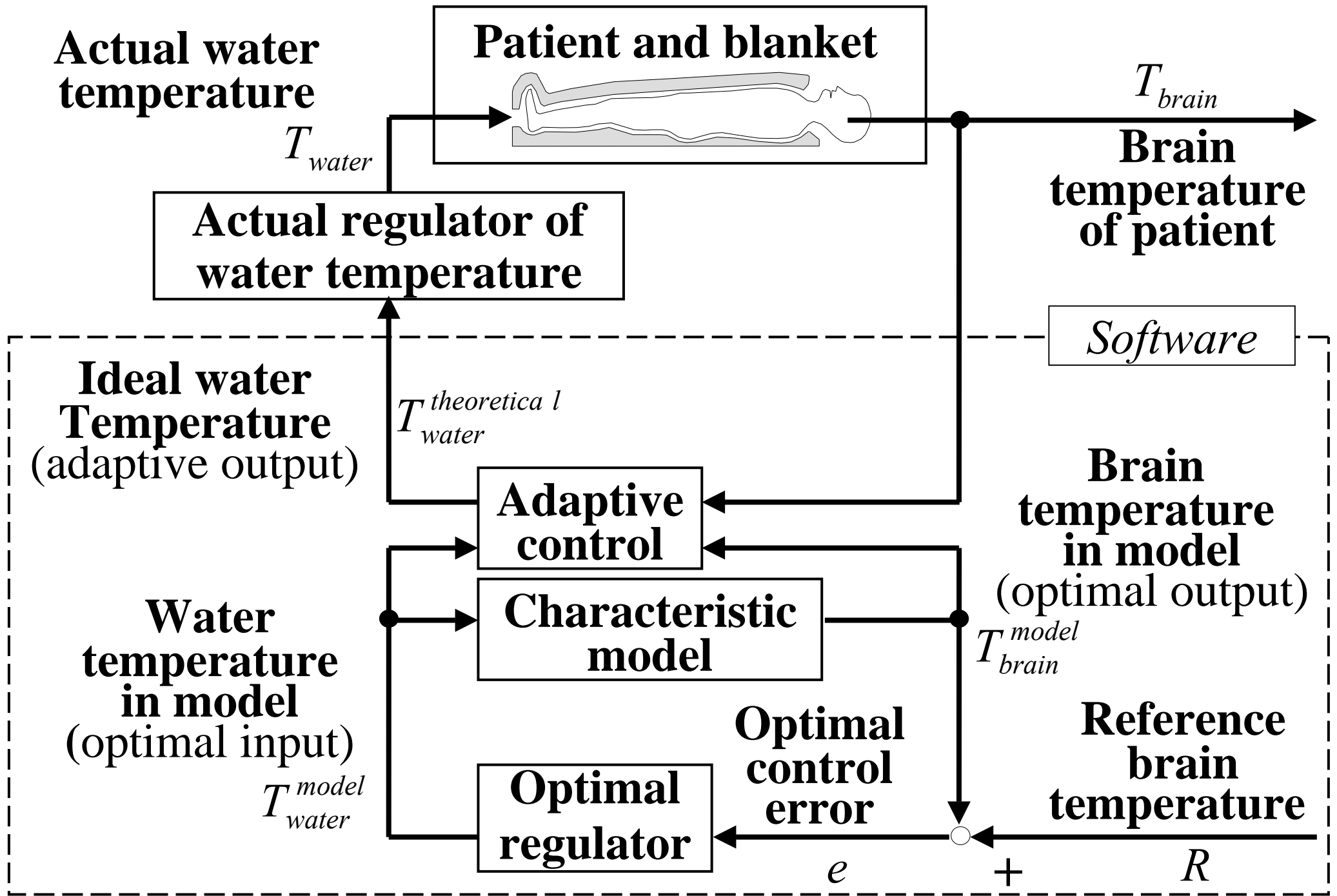
Control box of circulation and metabolism

Monitor

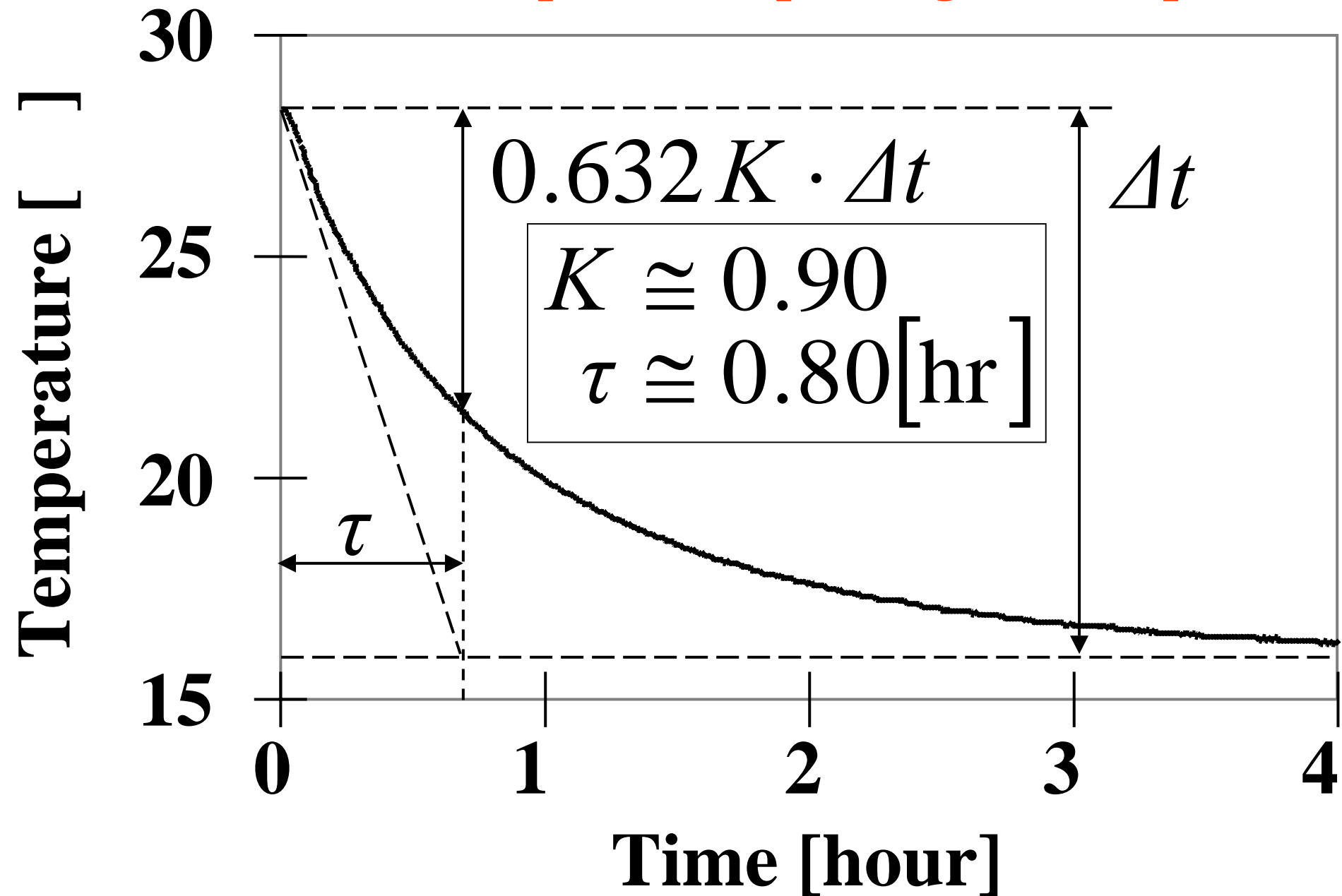
Automatic control apparatus

Mannequin in place of patient with cooling blanket





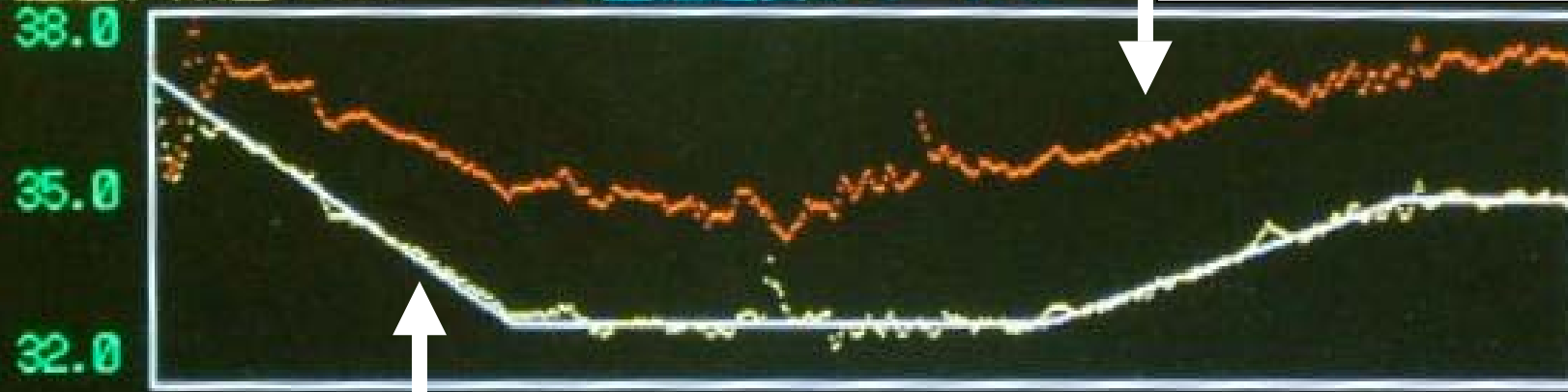
Characteristics of Mannequin to Step change of Temperature



脳温、体温 [°C]

<全経過表示モード>

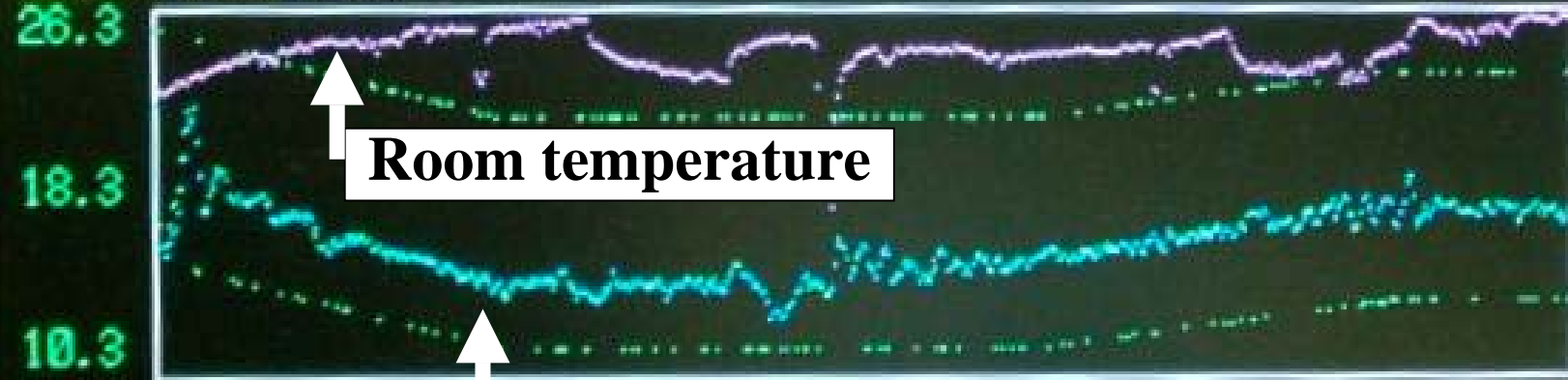
Body temperature



目標脳温=35.00
 実際脳温=35.00
 体温=37.44

Tracking of of brain temperature for desired brain temperature schedule

室温、水温 [°C]



室温=26.17
 目標水温=23.61
 実際水温=18.87

Room temperature

Water temperature of blanket

0 16 32 [時間]

システム状態 — 規範冷却方式

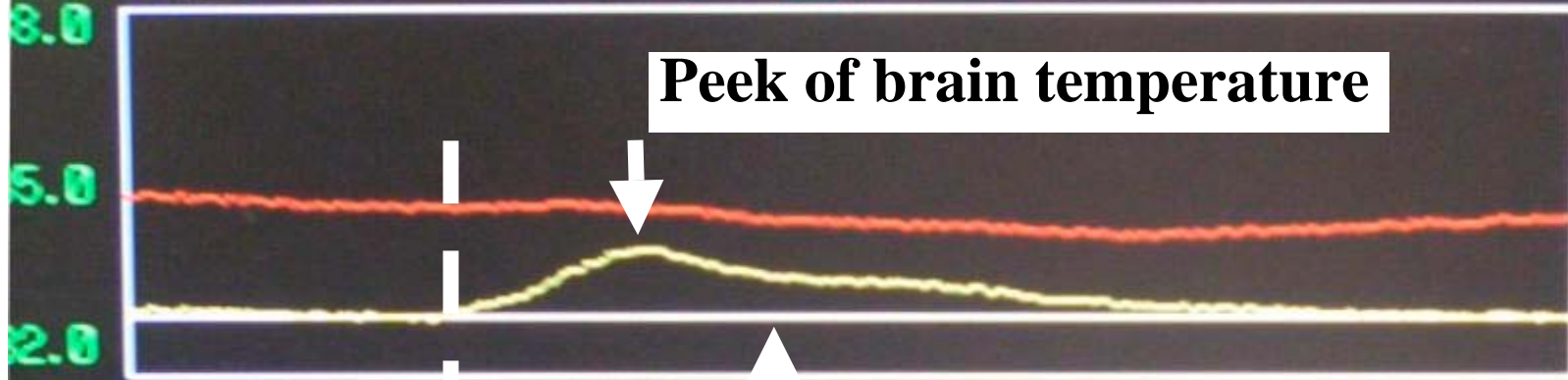
終了 [ESC] リセット

総冷却時間 32:00:00

サンプル数 2887

室温、体温 [°C]

<トレンド表示モード>



Peak of brain temperature

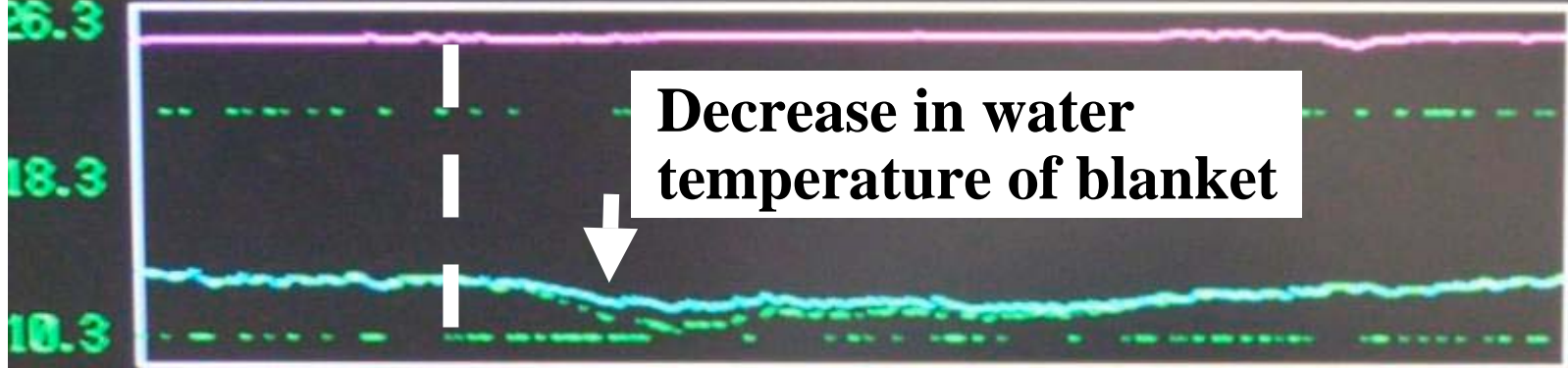
目標脳温=33.00

実際脳温=32.95

体温 =34.56

Desired brain temperature schedule

室温、水温 [°C]



Decrease in water temperature of blanket

室温 =25.05

目標水温=14.36

実際水温=14.36

Heater SW ON

0 30 60 [分]

システム状態 規範方式冷却

終了

リセット

総冷却時間14:25: 3

サンプル数

12976

脳温、体温 [°C]

<トレンド表示モード>

Body temperature

Brain temperature

目標脳温=33.00
 実際脳温=32.85
 体温=35.05

室温、水温 [°C]

Decrease in room temperature

室温=24.02
 目標水温=15.15
 実際水温=15.09

Opening the door

Water temperature of blanket

-----システム状態-----規範方式冷却-----

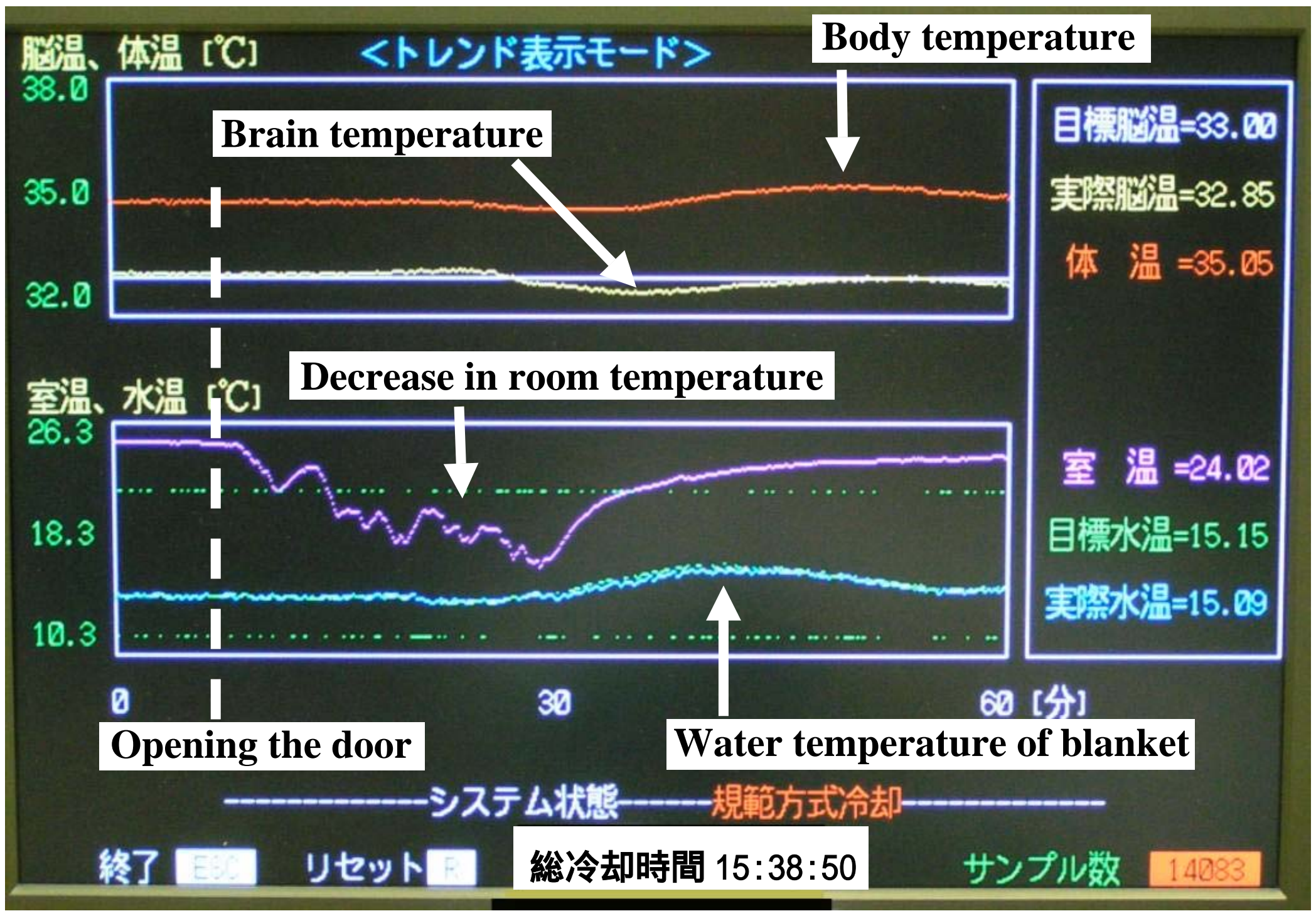
終了 EBC

リセット R

総冷却時間 15:38:50

サンプル数

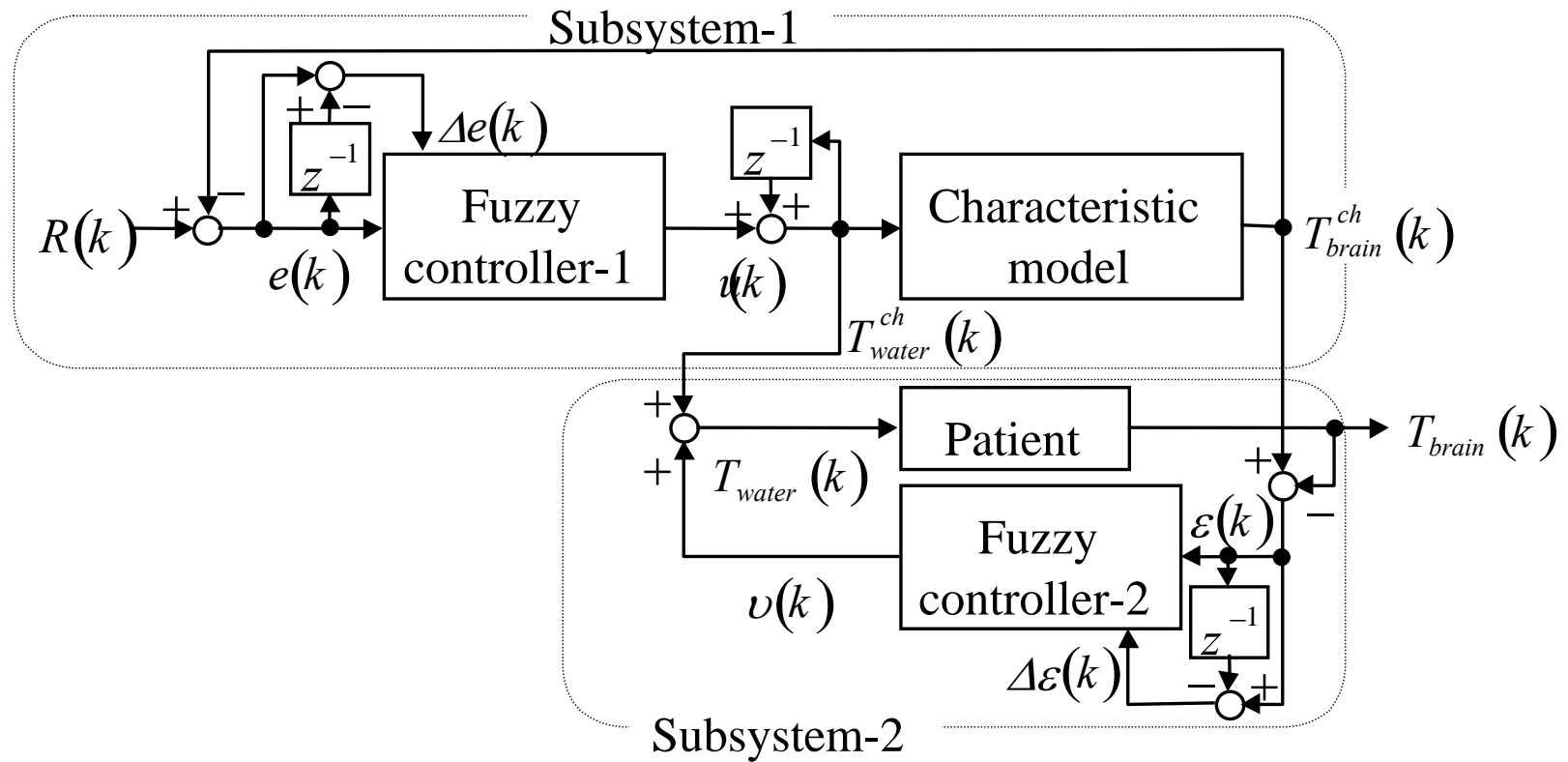
14083



Fuzzy Control of Brain Temperature by Water-Cooling System

**Biophysical System Engineering
Graduate School of Allied Health Sciences
Tokyo Medical and Dental University**

H.Wakamatsu, T.Wakatsuki, T.Utsuki

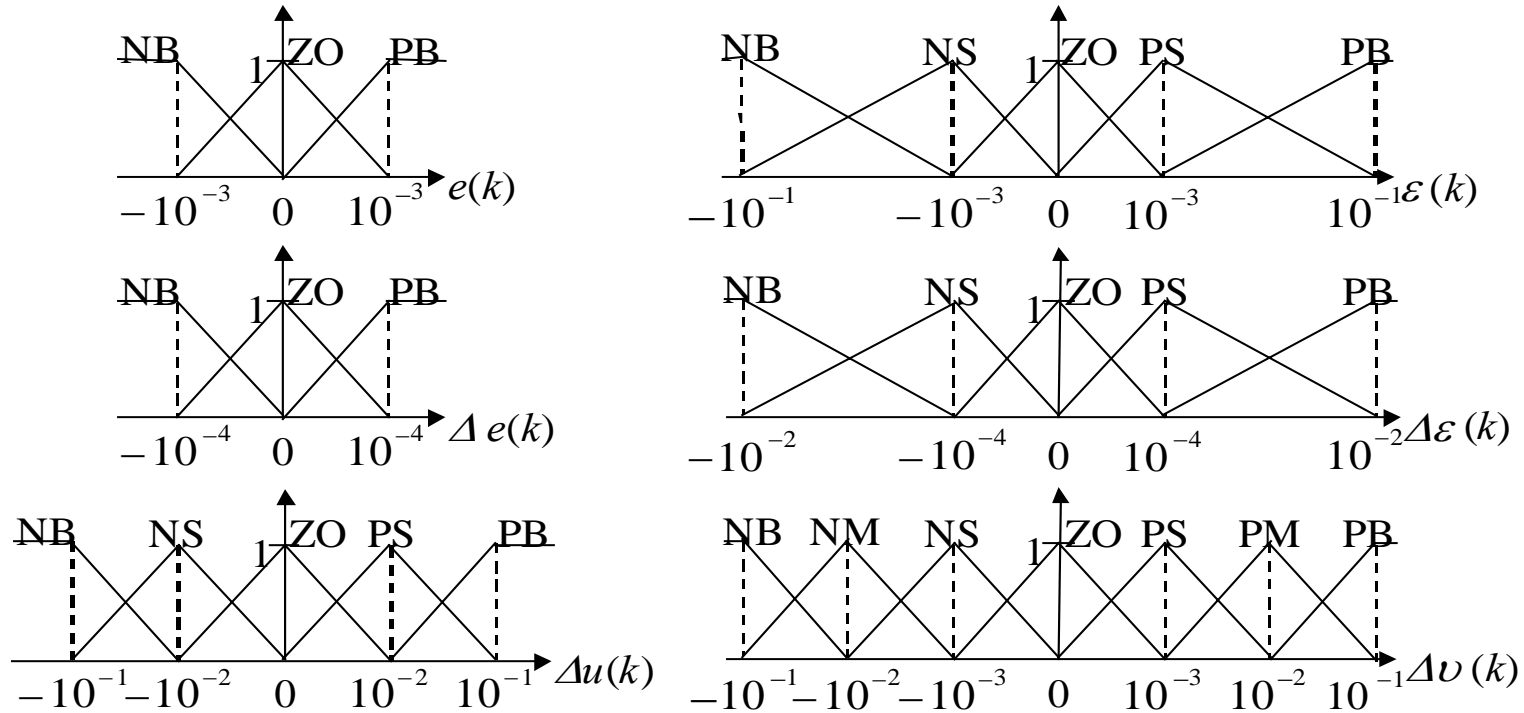


Block Diagram of Fuzzy Control System of Brain Temperature

Membership Function and Inference Rule for the Experiment

Using Mathematical Model

Sampling period = 4[sec]

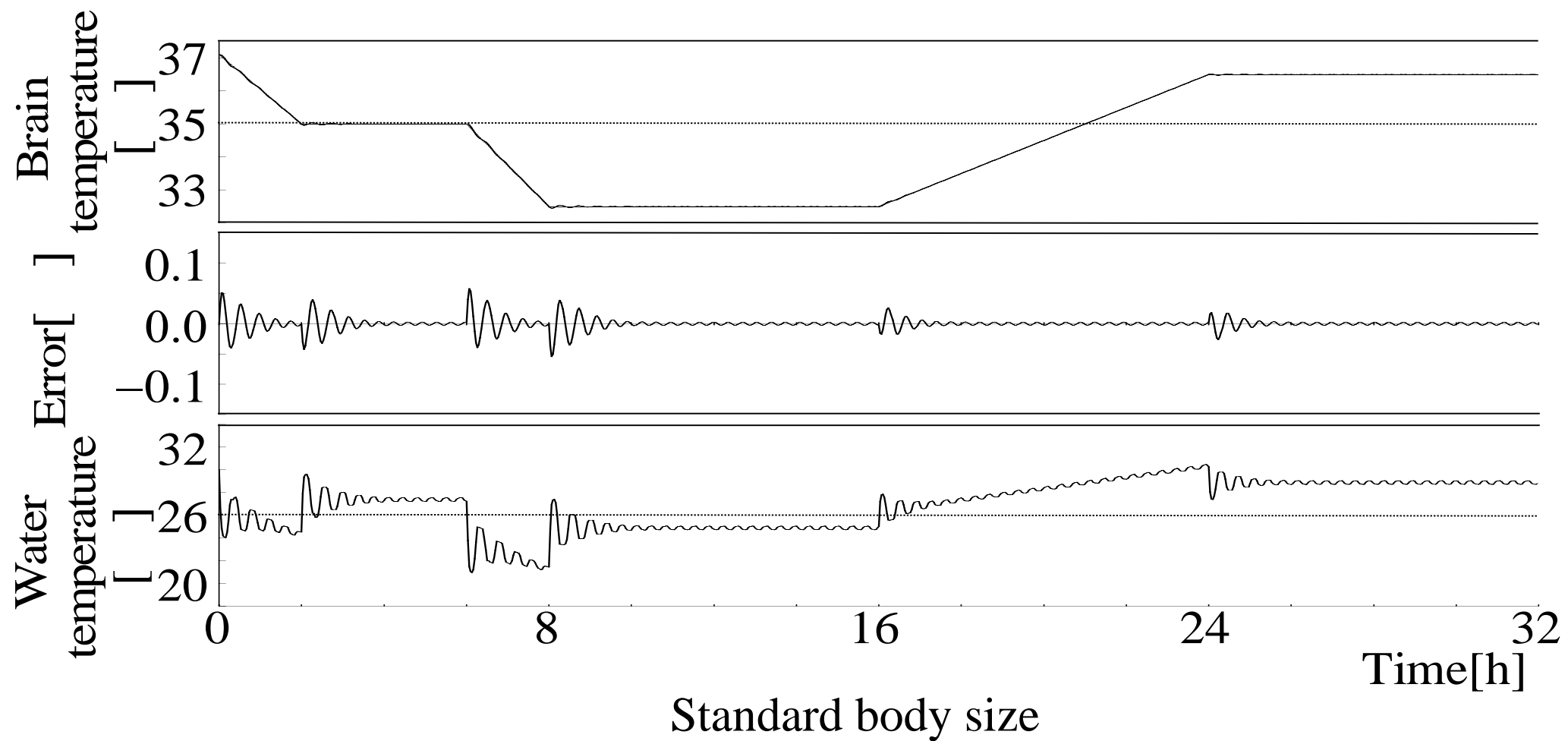


$\Delta u(k)$		$e(k)$		
		PB	ZO	NB
$\Delta e(k)$	PB	PB	PS	ZO
	ZO	PS	ZO	NS
	NB	ZO	NS	NB

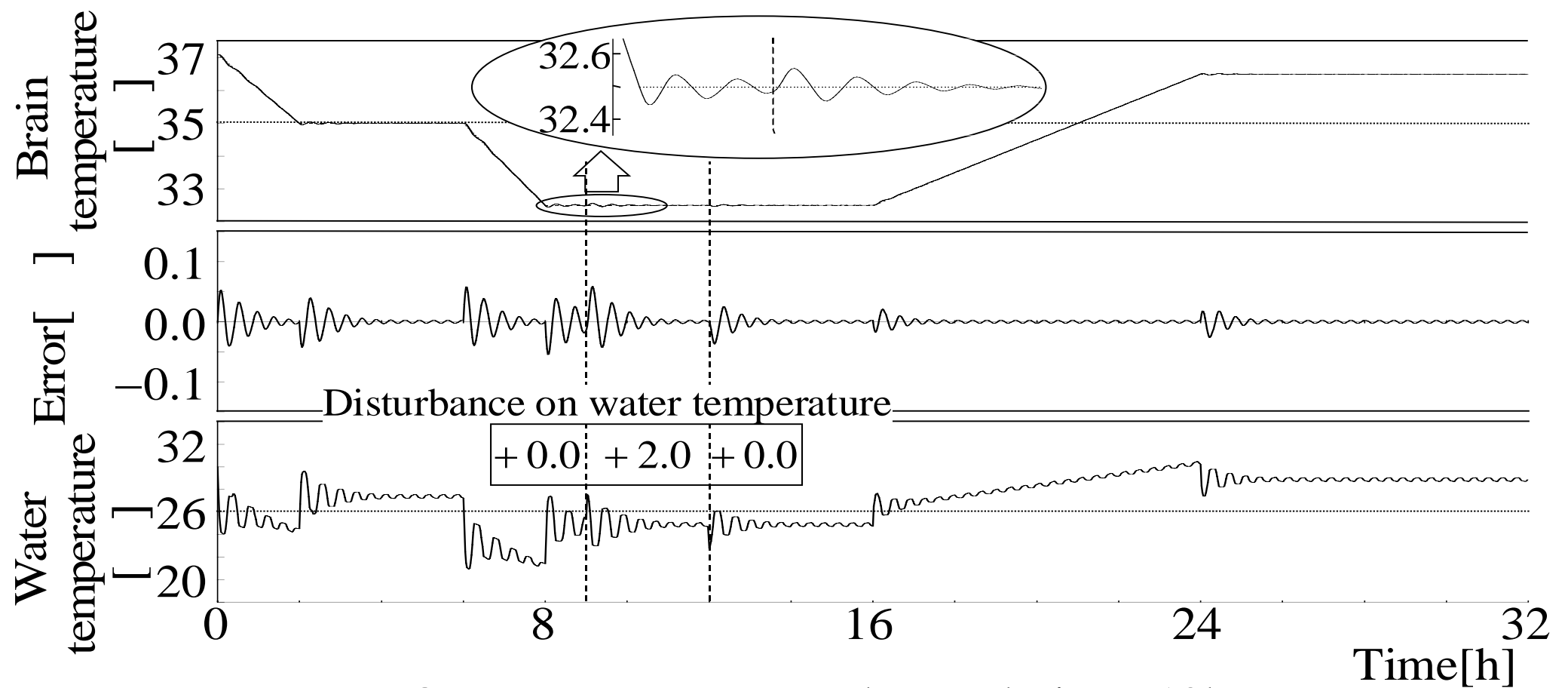
Fuzzy Controller-1

$\Delta v(k)$		$\varepsilon(k)$				
		PB	PS	ZO	NS	NB
$\Delta \varepsilon(k)$	PB	PB	PB	PM	PS	ZO
	PS	PB	PM	PS	ZO	NS
	ZO	PM	PS	ZO	NS	NM
	NS	PS	ZO	NS	NM	NB
	NB	ZO	NS	NM	NB	NB

Fuzzy Controller-2

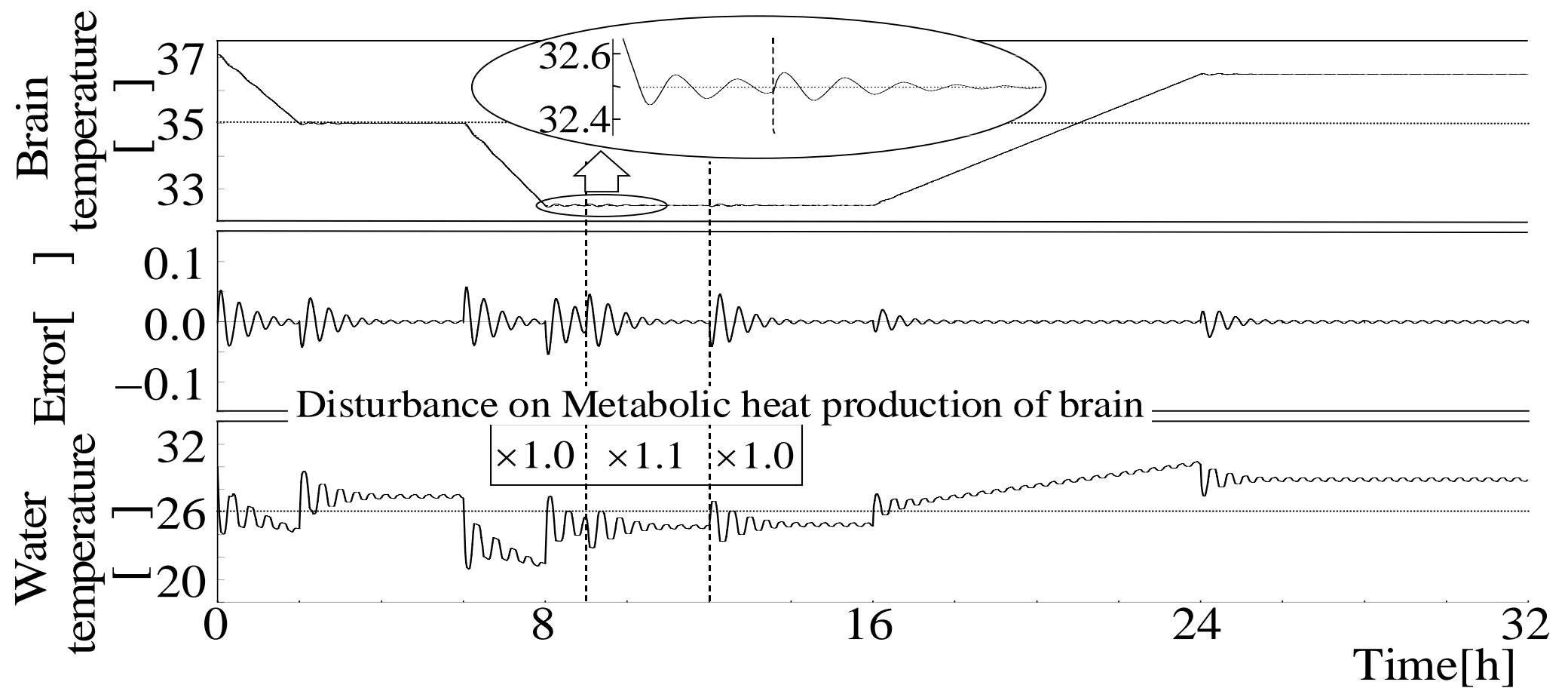


Controlled dynamics of brain and water temperature



On water temperature change during 9-12 hour
from the beginning of experiment.

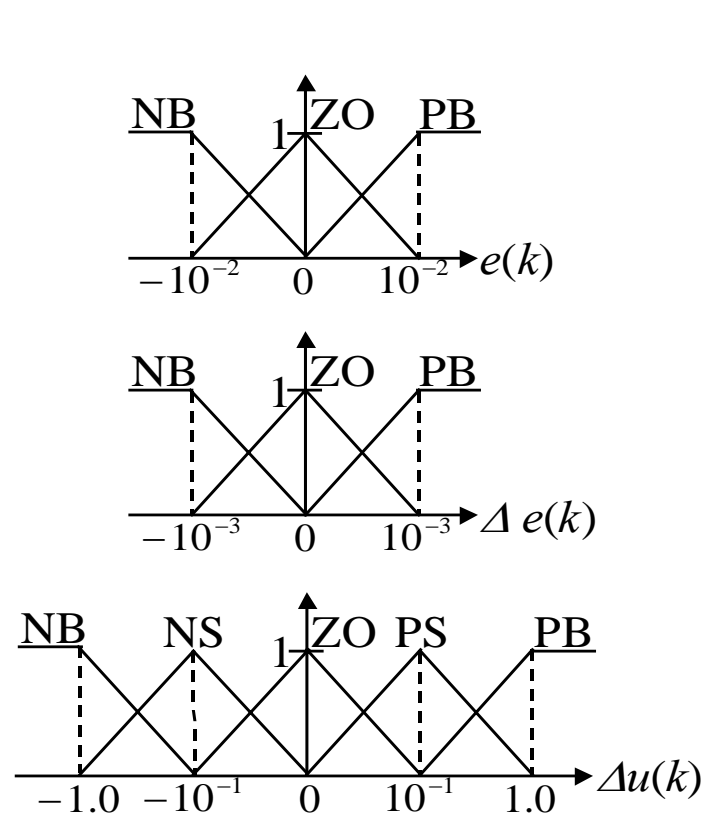
Controlled dynamics of brain and water temperature



On metabolic rate change during 9-12 hour
from the beginning of experiment.

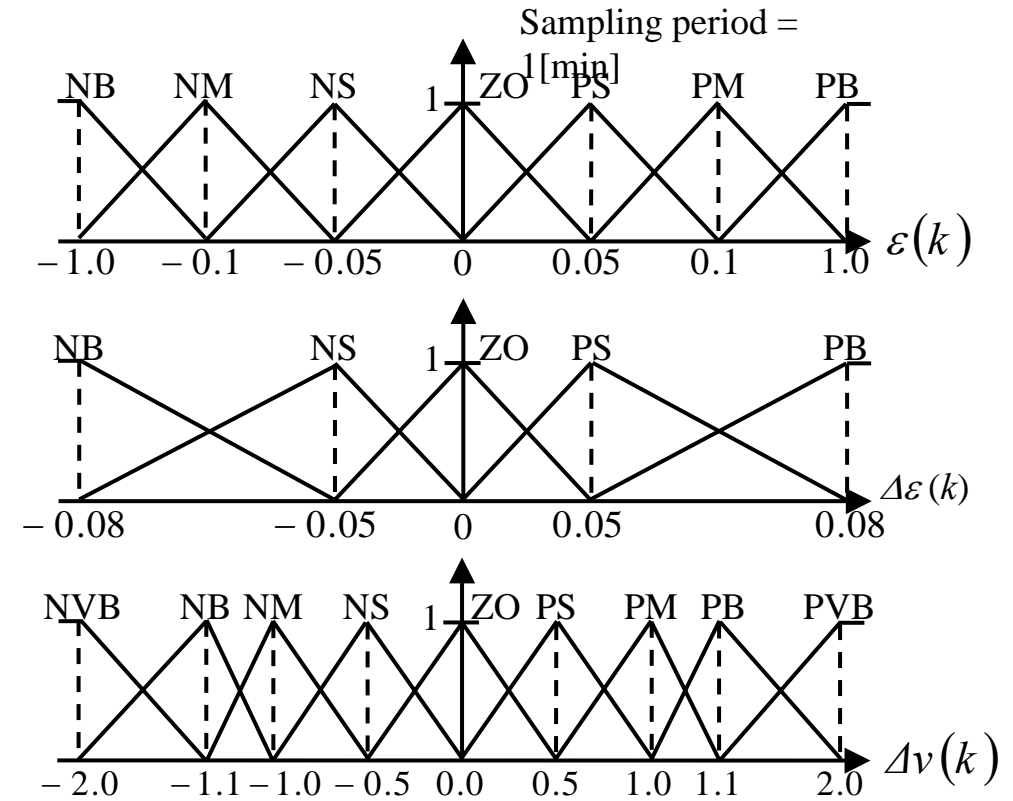
Controlled dynamics of brain and water temperature

Membership Function and Inference Rule for the Experiment Using Mannequin



$\Delta u(k)$		$e(k)$		
		PB	ZO	NB
$\Delta e(k)$	PB	PB	PS	ZO
	ZO	PS	ZO	NS
	NB	ZO	NS	NB

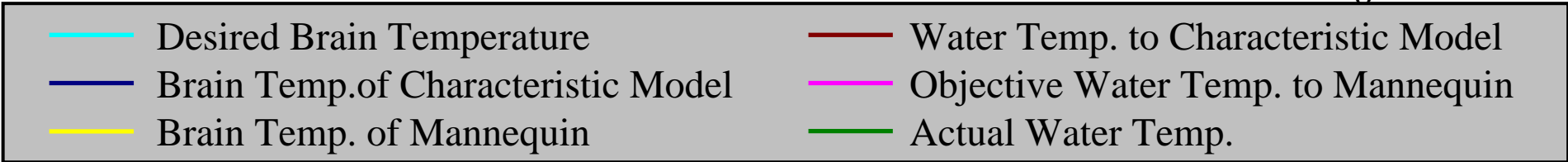
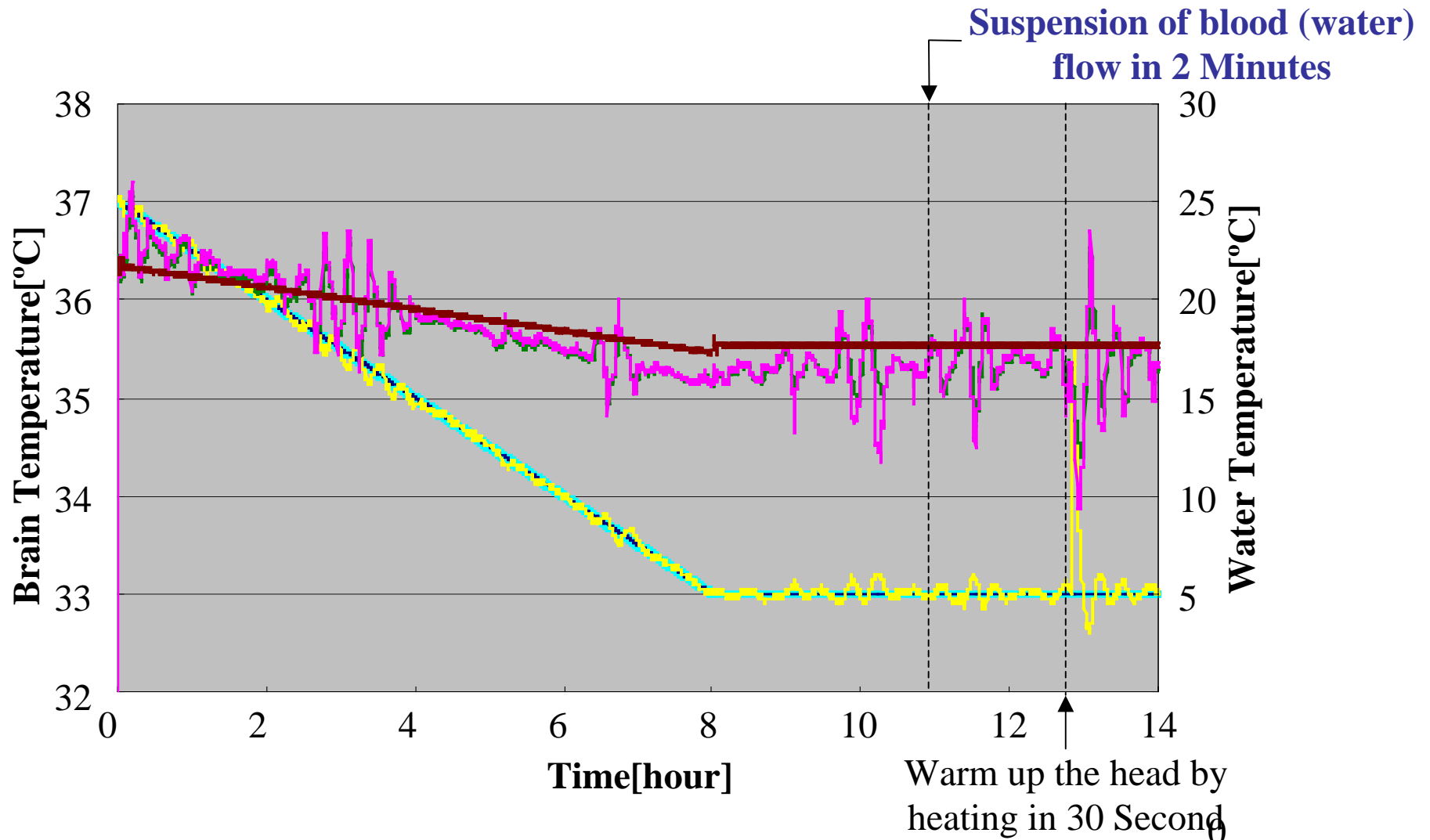
Fuzzy Controller-1



$\Delta v(k)$		$\varepsilon(k)$						
		PB	PM	PS	ZO	NS	NM	NB
$\Delta \varepsilon(k)$	PB	PVB	PVB	PS	ZO	PVB	PVB	PVB
	PS	PVB	PVB	PS	ZO	PM	PB	PVB
	ZO	PVB	ZO	ZO	ZO	ZO	ZO	NVB
	NS	NVB	NB	NM	ZO	NS	NVB	NVB
	NB	NVB	NVB	NVB	ZO	NS	NVB	NVB

Fuzzy Controller-2

Experimental Result during Cooling and Stable Period

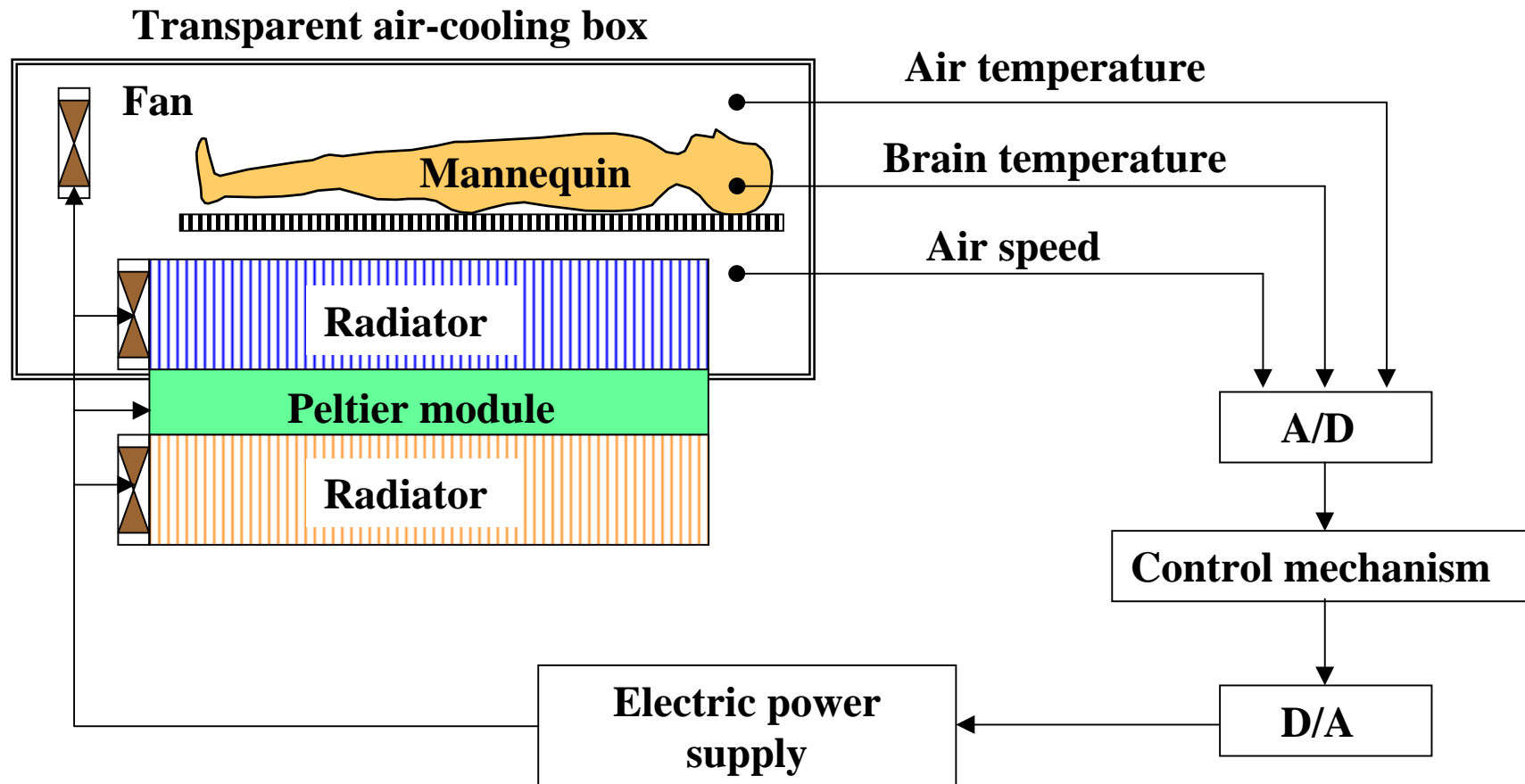


Control of Brain Temperature by Air-Cooling System

**Biophysical System Engineering
Graduate School of Allied Health Sciences
Tokyo Medical and Dental University**

H.Wakamatsu, T.Utsuki, T.Wakatsuki

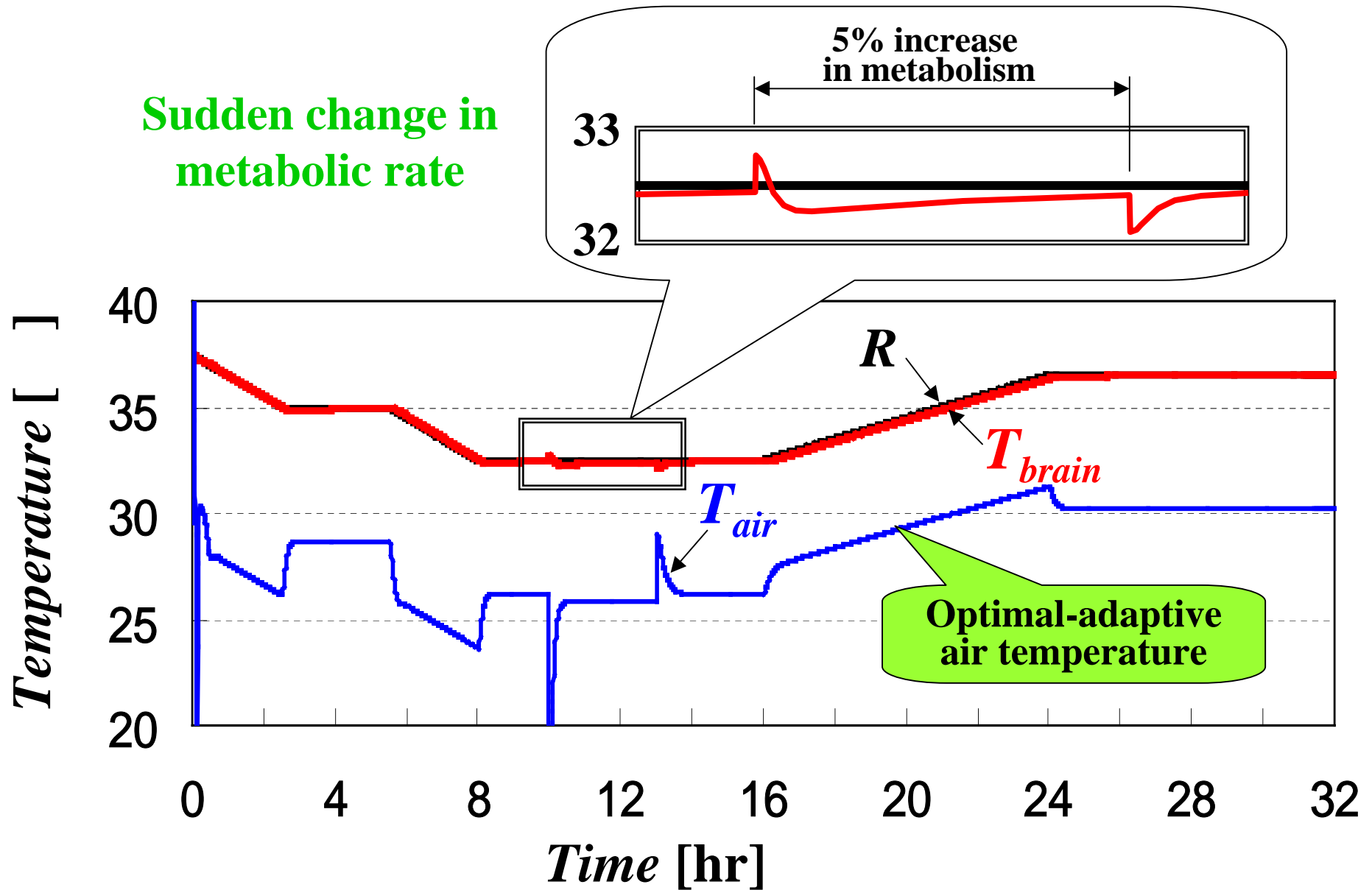
Air-cooling Incubating System



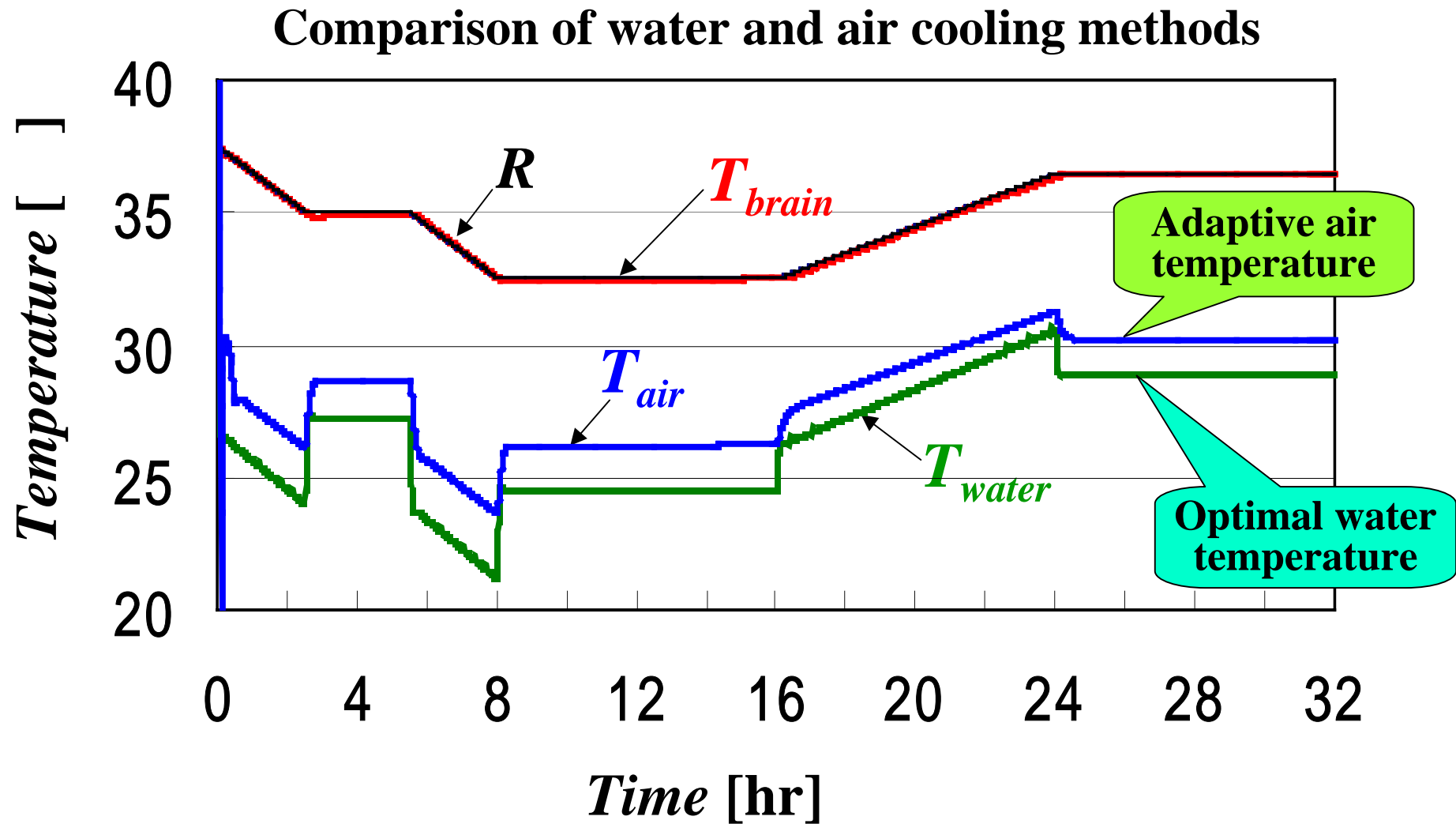
Automatic Air-Cooling Incubating System for Brain Hypothermia Treatment



Air-cooling Simulation Result



Simulation Result



AUTOMATIC CONTROL OF RESPIRATION TO DEAL WITH DIFFERENCE OF INDIVIDUAL CHARACTERISTICS

**H. Wakamatsu, K. Takahara
Biophysical System Engineering,
Graduate School of Medicine,
Tokyo Medical and Dental University, Japan**

Overview of Talk

- **Development of a Basic Control System for Controlled and Assisted Respiration**
- **Experimental Confirmation on Automatic Control of Alveolar CO₂-concentration**

Background

Automatic Control of Organic Functions

- Organic Function -

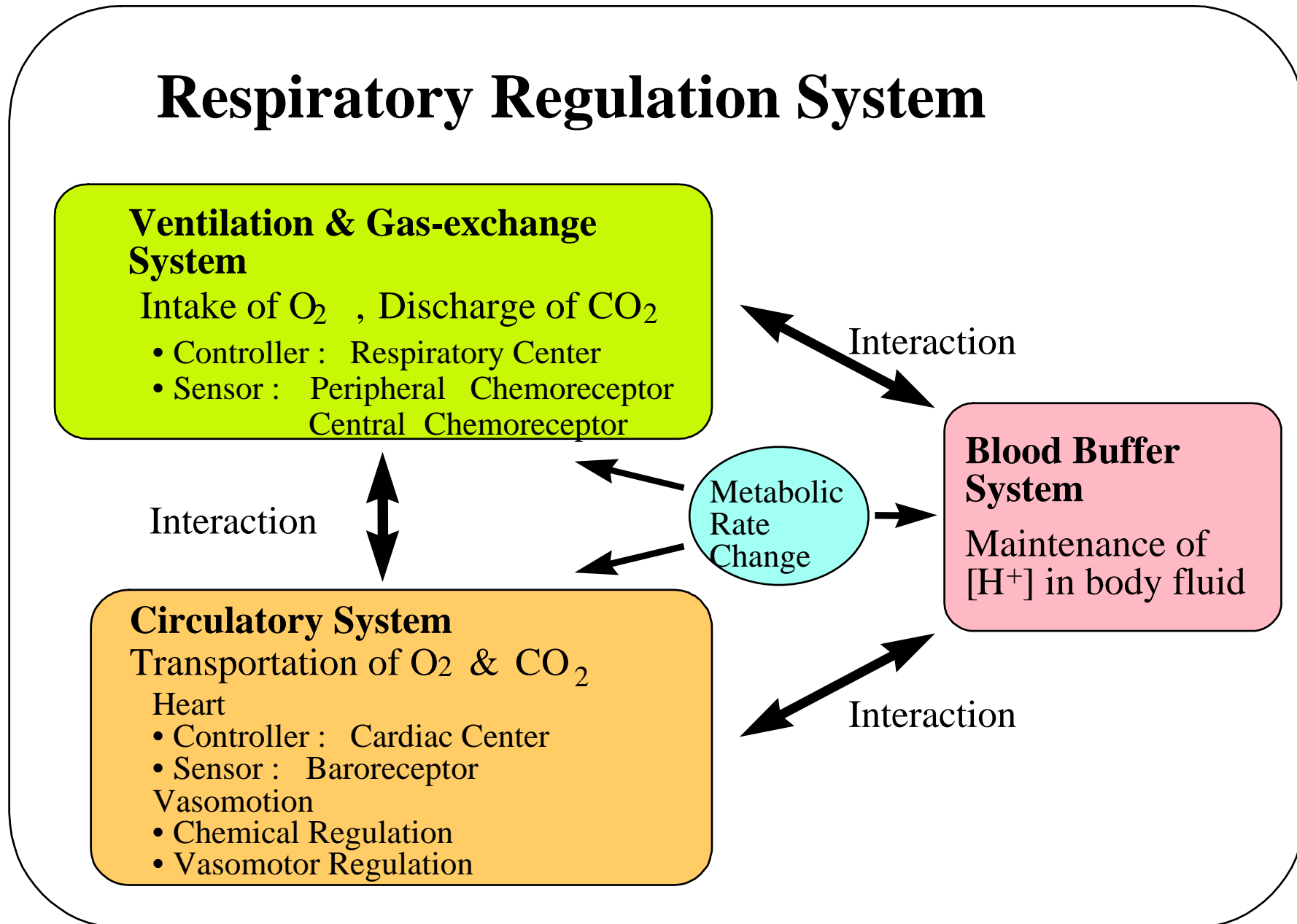
- A Controlled Object with Controllers
- Remarkable Characteristics in Organisms

Non-linearity, Chronic Change , Individuality

- Respiratory Regulation System -

- Possibility of Measurement and Control
Non-invasively and at Real-Time

Respiratory Regulation System



Points of Design of the Control System

Respiratory Regulation System

- Non-linearity
- Chronic Change
- Individuality
- **Change of Environment**

↓ In order to control

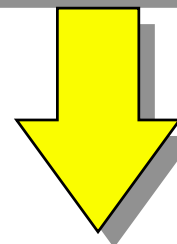
- Understanding by Detection of Its Characteristics
- Design of Control System based on Detected Characteristics

Introduction of an
“Adaptive System”

Significance of the Control System Based on Adaptive Method

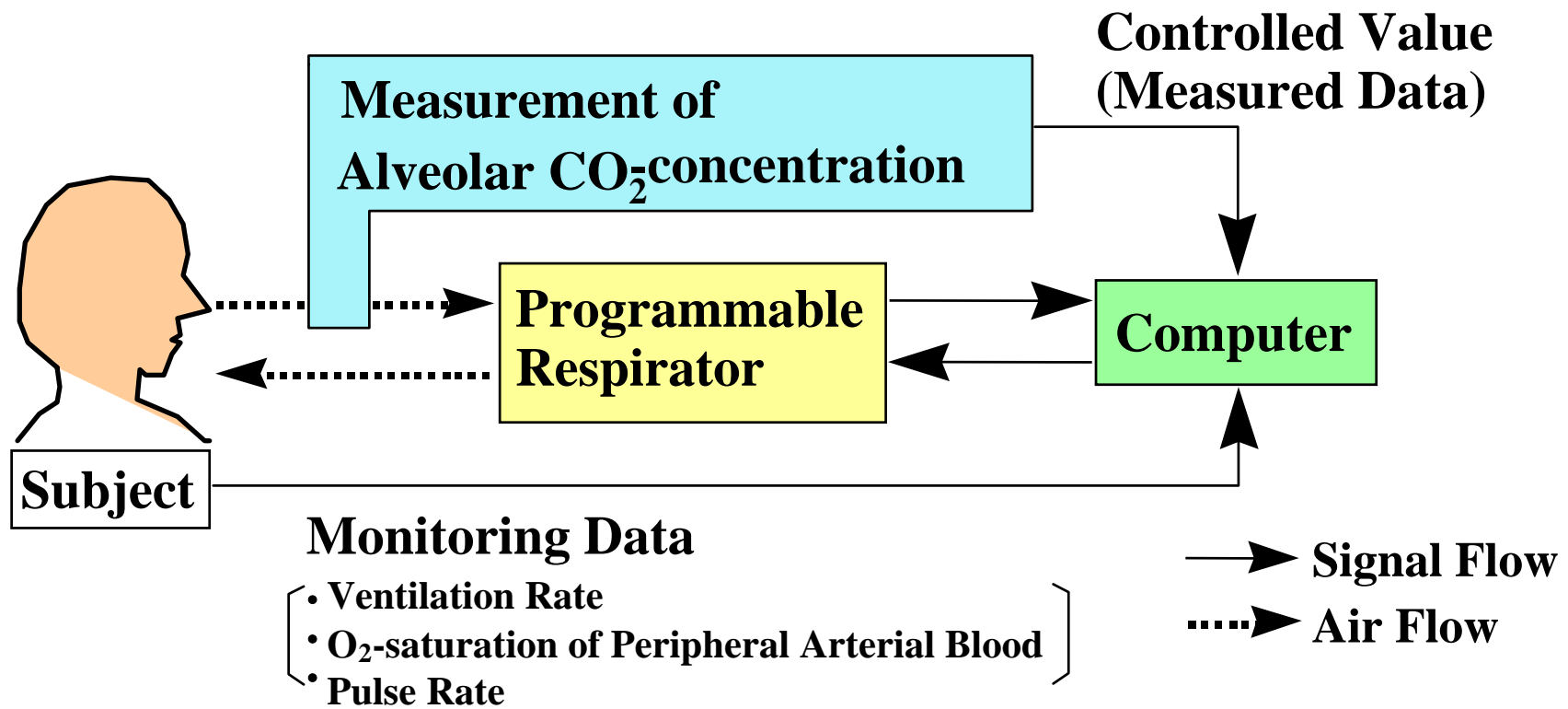
Respiratory Regulation System

- **Non-linearity**
- **Chronic Change**
- **Individuality**
- **Change of Environment**



Included in

**Deviations of the Parameters of
the Mathematical Model**



Concept of the control system of artificial respiration

Technological assumption for the design of control system of respiratory regulation system

[1] The dynamics of a respiratory system is assumed to be characterized by the relation of input (ventilation rate) and output (alveolar CO₂-concentration).

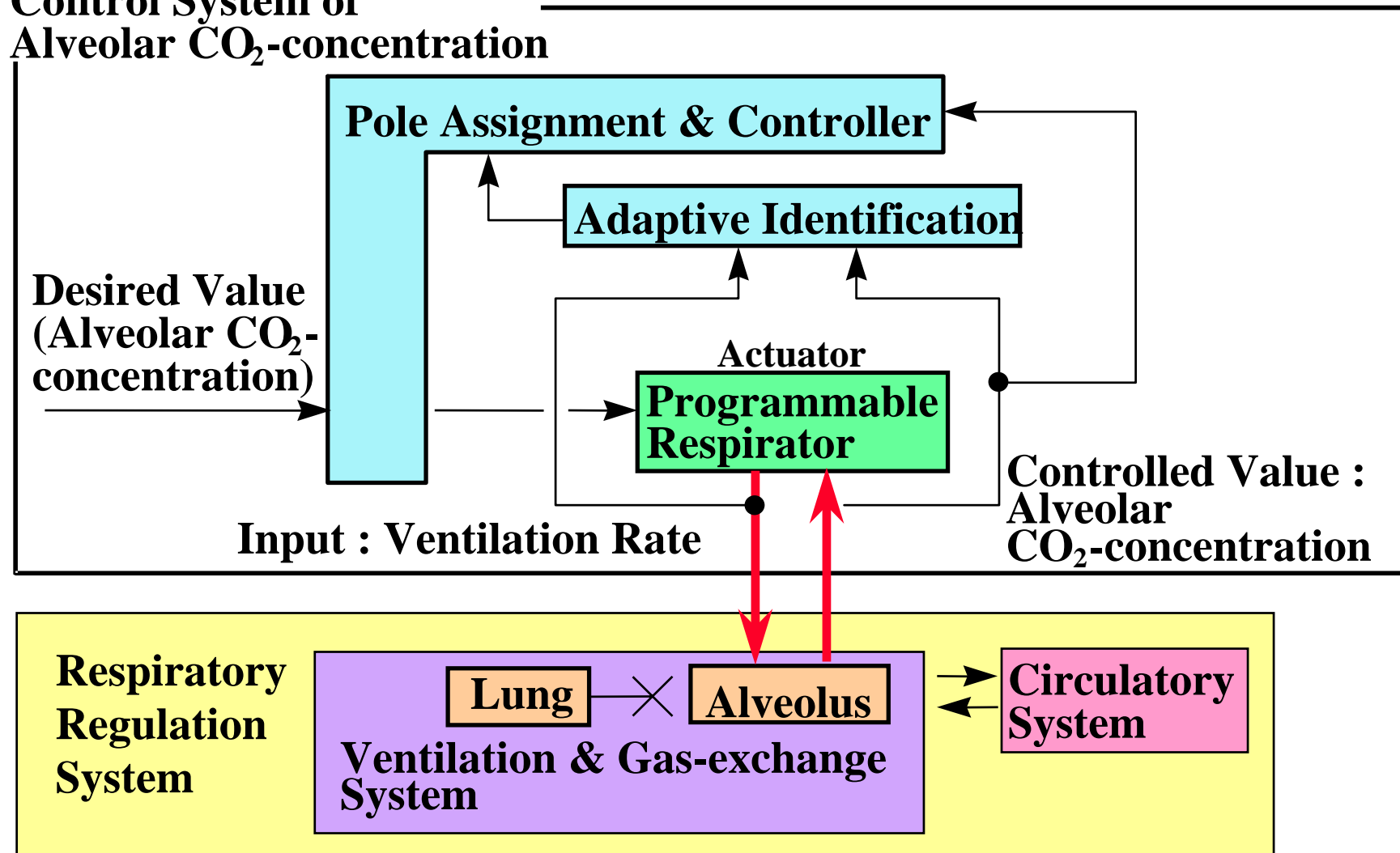
[2] No consideration of the effect of interaction of ventilation rate with metabolic rate on alveolar CO₂-concentration.

[3] Contribution of metabolic rate change to output is regarded as a characteristic change resulting from parameter deviation.

Design of Control System Coping with Ambiguous Knowledge about Respiratory Regulation System

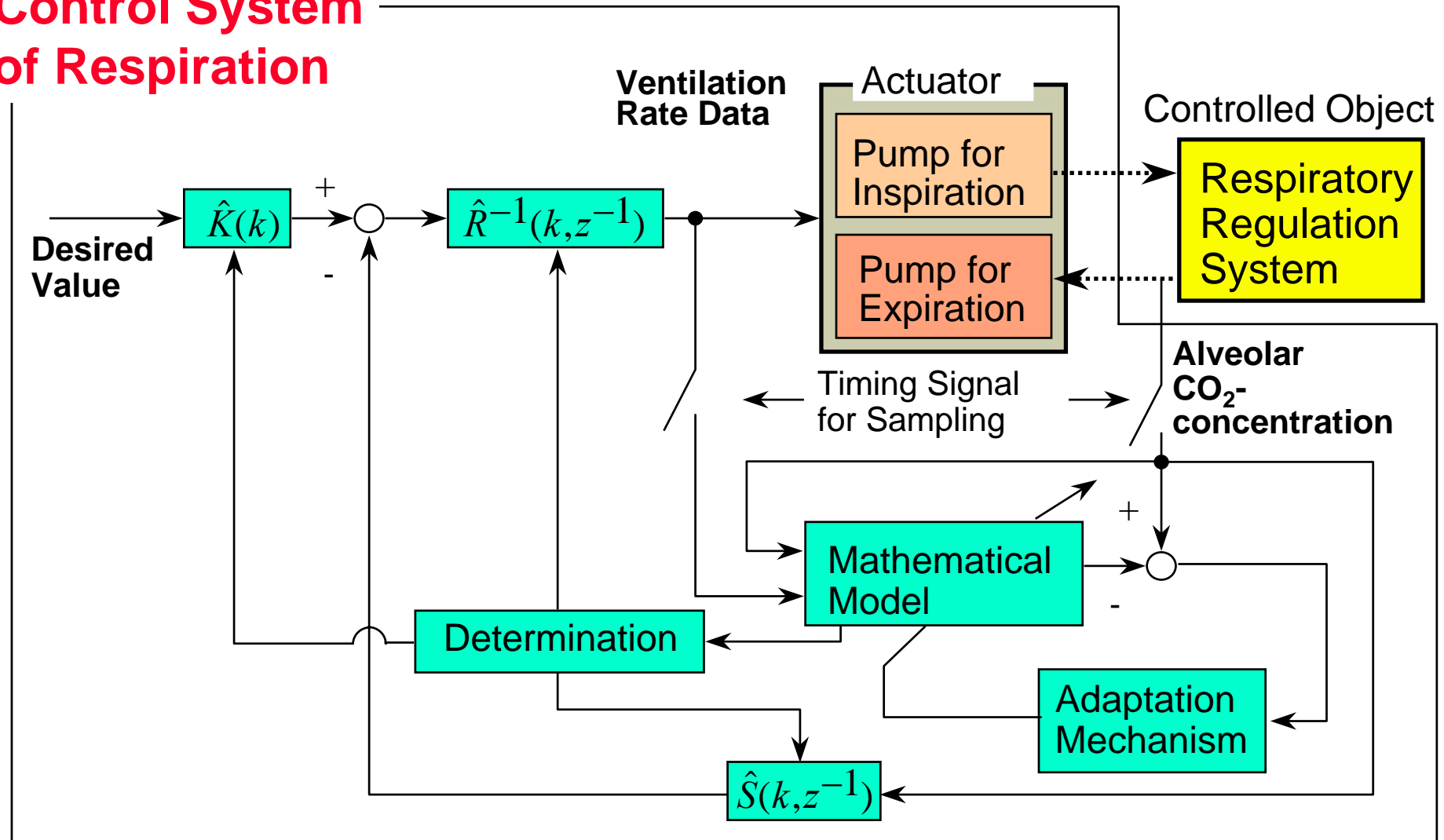
The control system of a respiration is designed only on the assumption of its description by the appropriate mathematical model that may represent essential characteristics of a respiratory system including characteristics of experimental equipment (Wakamatsu, *et al.*, 1990)

Control System of Alveolar CO₂-concentration



Adaptive control system of a respiration using pole assignment method

Control System of Respiration



Block-diagram of control system of alveolar CO₂-concentration



Interior view of the all-built-in-one type respirator



Developed all-built-in-one type respirator

Assisted Respiration and Its Digital Control

Assisted respiration

: Depending on a patient's
Spontaneous respiratory rhythm

Sampling interval

Constant



Disagreement of sampling
Time with measuring time
of alveolar CO_2 -concentration

Synchronized with
respiratory rhythm



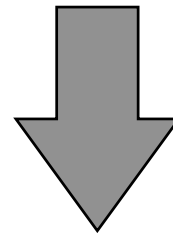
Distorted recognition of the
characteristics depending on
the sampling interval

Significance of Adaptive System in **Assisted Respiration**

Respiratory regulation system

- Non-linearity
- Chronic changes
- Individuality
- Change of environment

Distorted recognition of
the characteristics depending
on sampling interval



Included in

Deviations of the parameters of
The mathematical model

Controlled Respiration and Its Digital Control

Controlled respiration

: Respiratory rhythm set by medical staff

Sampling interval

Constant

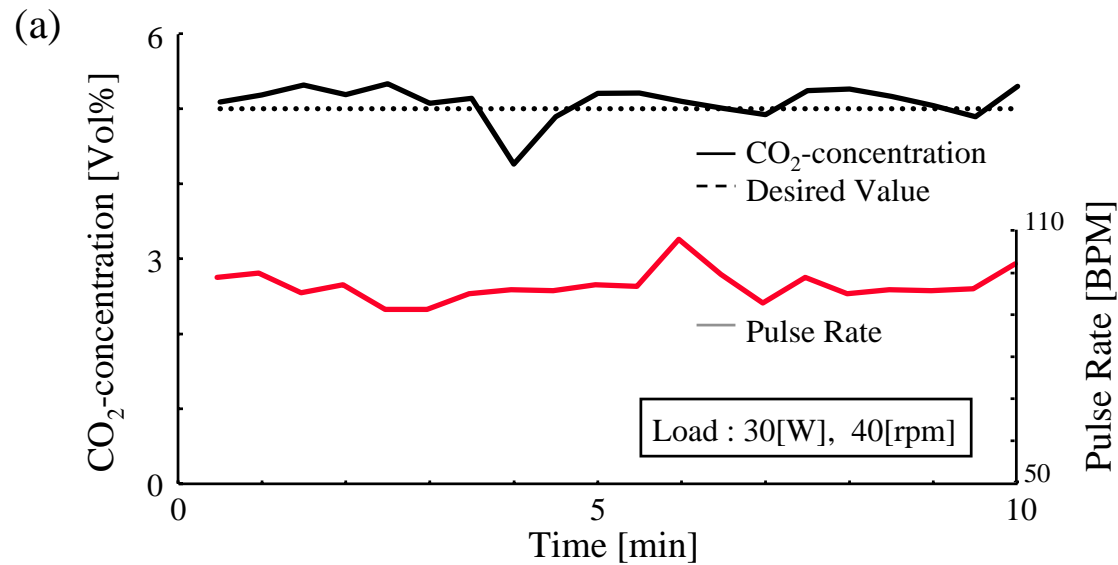


No difficulty in controlling

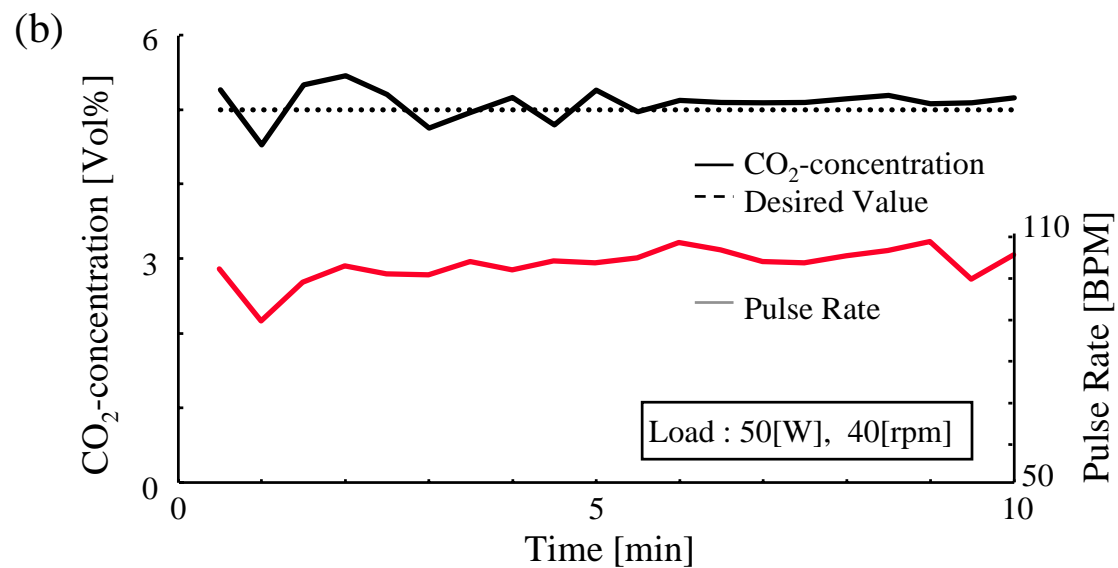
Experiment

- Subjects : Healthy Persons
(Male:7, Female:2, Age:27-38)
- Breathing : Lacking Own Respiratory Rhythm and Supported by the Respirator
- Desired Value : Step-like Function Decreased by 1.0[Vol%] after 10[min] from the Start of the Experiment

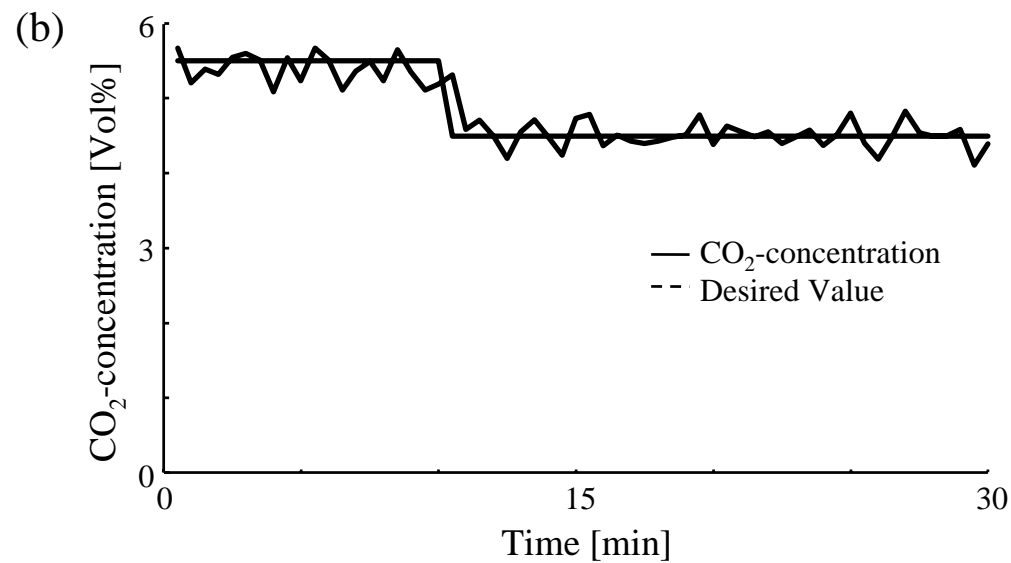
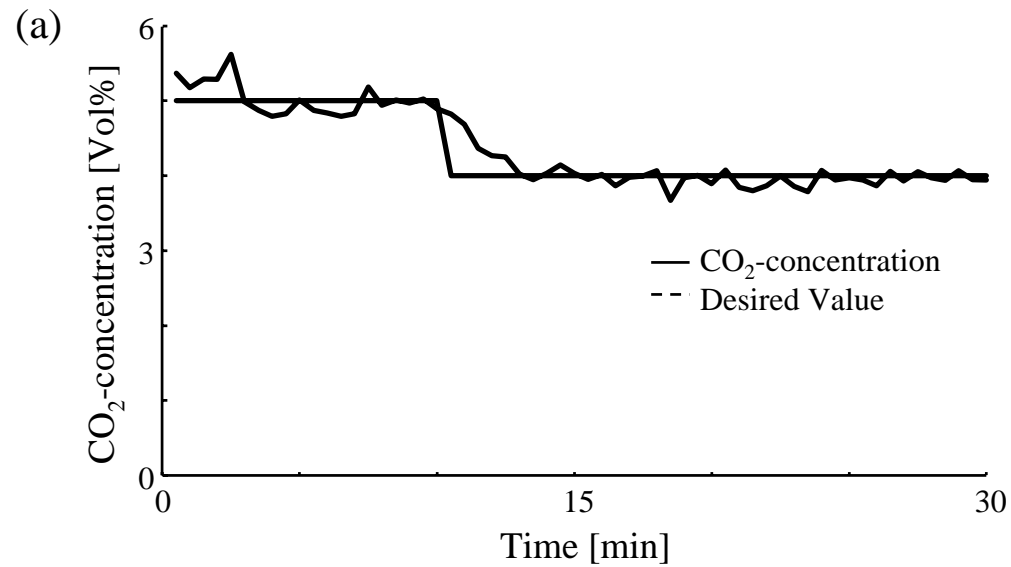
Controlled Respiration During Light Exercise



- Sampling Interval : 30 [sec]
- Respiration Rate : 22 [times/min]
- Period of Experiment : 10 [min]

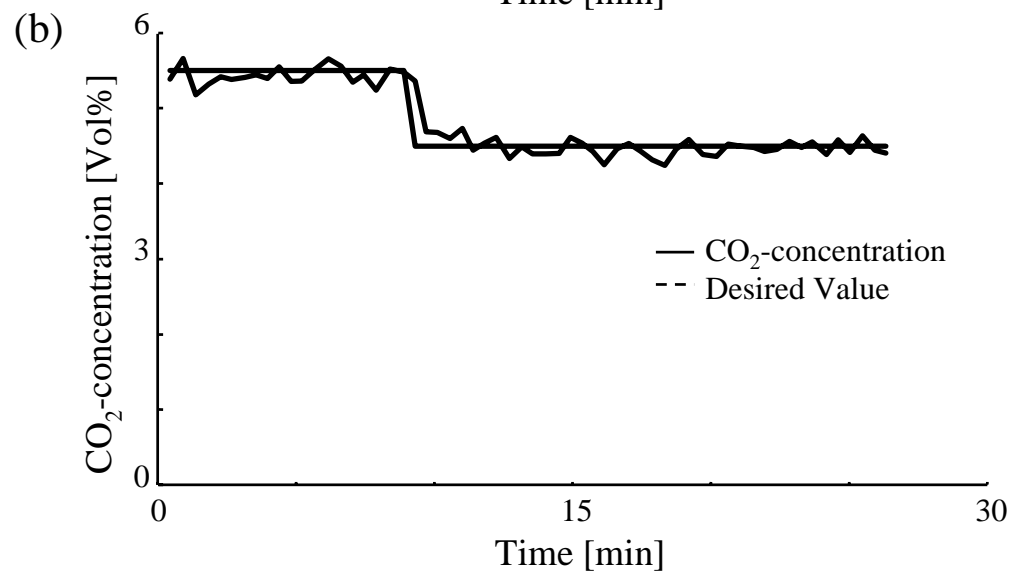
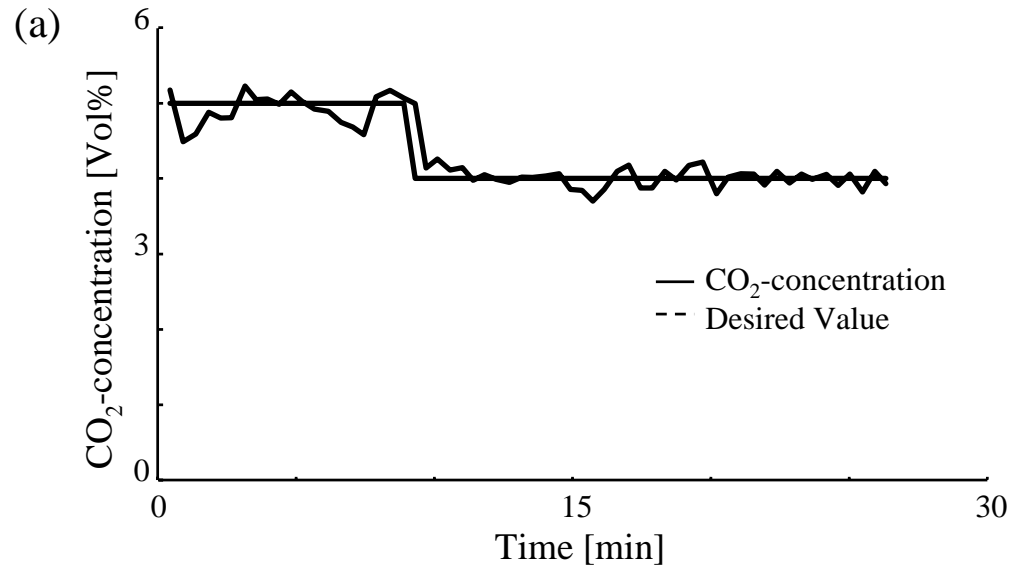


Controlled Respiration at Rest

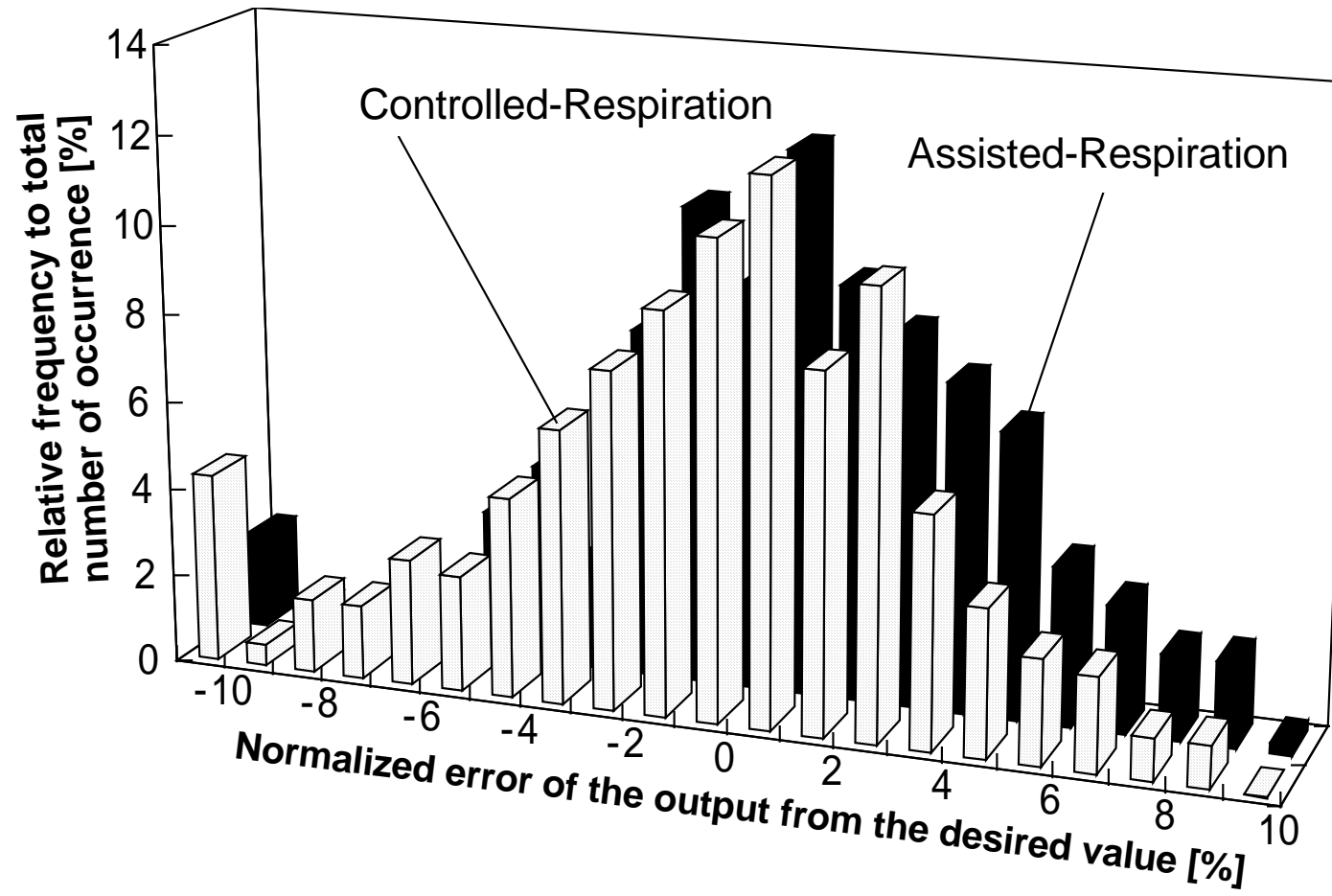


- Sampling Interval : 30 [sec]
- Respiration Rate : 16 [times/min]
- Period of Experiment : 30 [min]

Assisted Respiration



- **Variable Sampling Interval :**
Every 7 Ventilatory Periods
(23.3 ~ 30.0 [sec])
- **Respiration Rate :**
Changed at Random from
14 to 18 [times/min]



Distribution of errors of the outputs from the desired values.

Concluding Remarks

- **Development of a Computer-based Control System of Artificial Respiration by Adaptive Pole-Assignment Method.**
- **Clinical Possibility to Control the Respiratory Regulation System Irrespective of Metabolic Rate Changes in Different Subjects**

Additional Remark

Available to any patient whose dynamic characteristics cannot be completely Known

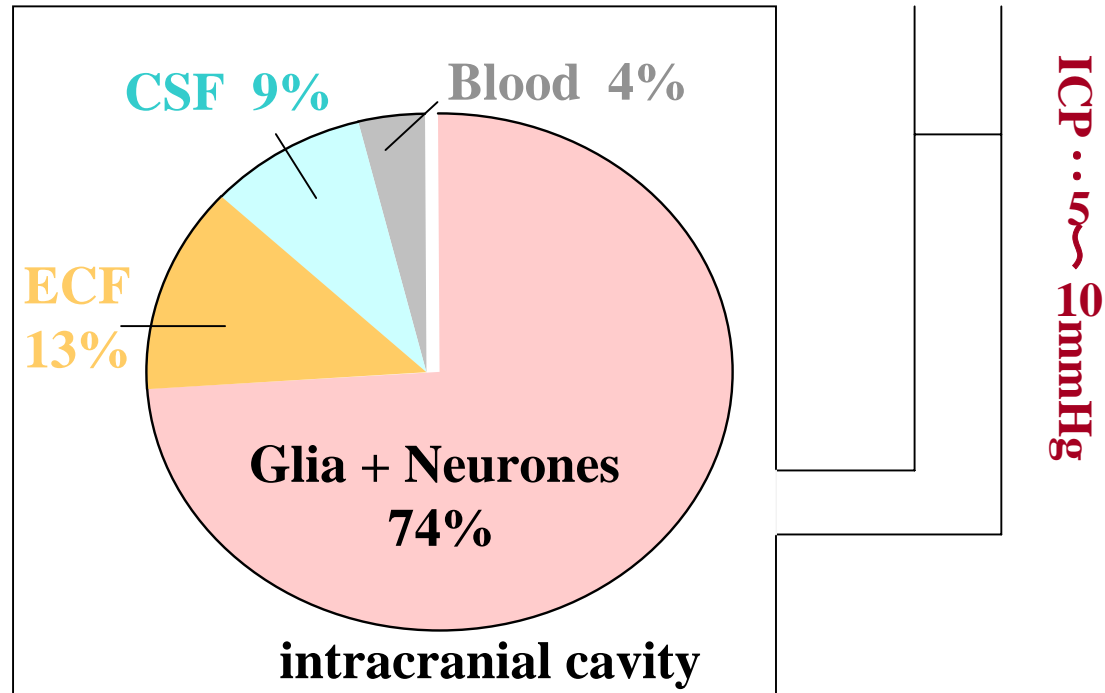
Generally useful to control of other organic functions

Control of Intracranial Pressure By Administration of Mannitol based on Mathematical Model

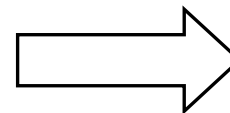
**Biophysical System Engineering,
Graduate School of Health Sciences,
Tokyo Medical and Dental University**

H.Wakamatsu, Ji Nan

Cause of Intracranial Hypertension



- ✧ **space-occupying lesions** (hematoma)
- ✧ **brain volume** ↑ (brain edema)
- ✧ **blood volume** ↑ (brain swelling)
- ✧ **CSF volume** ↑ (hydrocephalus)



> 15mmHg

Therapy of Intracranial Hypertension

. Surgical Treatments

External Decompression

Internal Decompression

Removal of Space-Occupying Mass

Drainage of CSF

. Conservative Treatments

Dehydrators (Osmotherapy)

Corticosteroids Therapy

Oxygen tent

Hypothermia

Barbiturate Therapy

Background and Aim of the Study

(Traumatic brain injuries , brain tumors, etc.)

Intracranial hypertension caused by brain edema

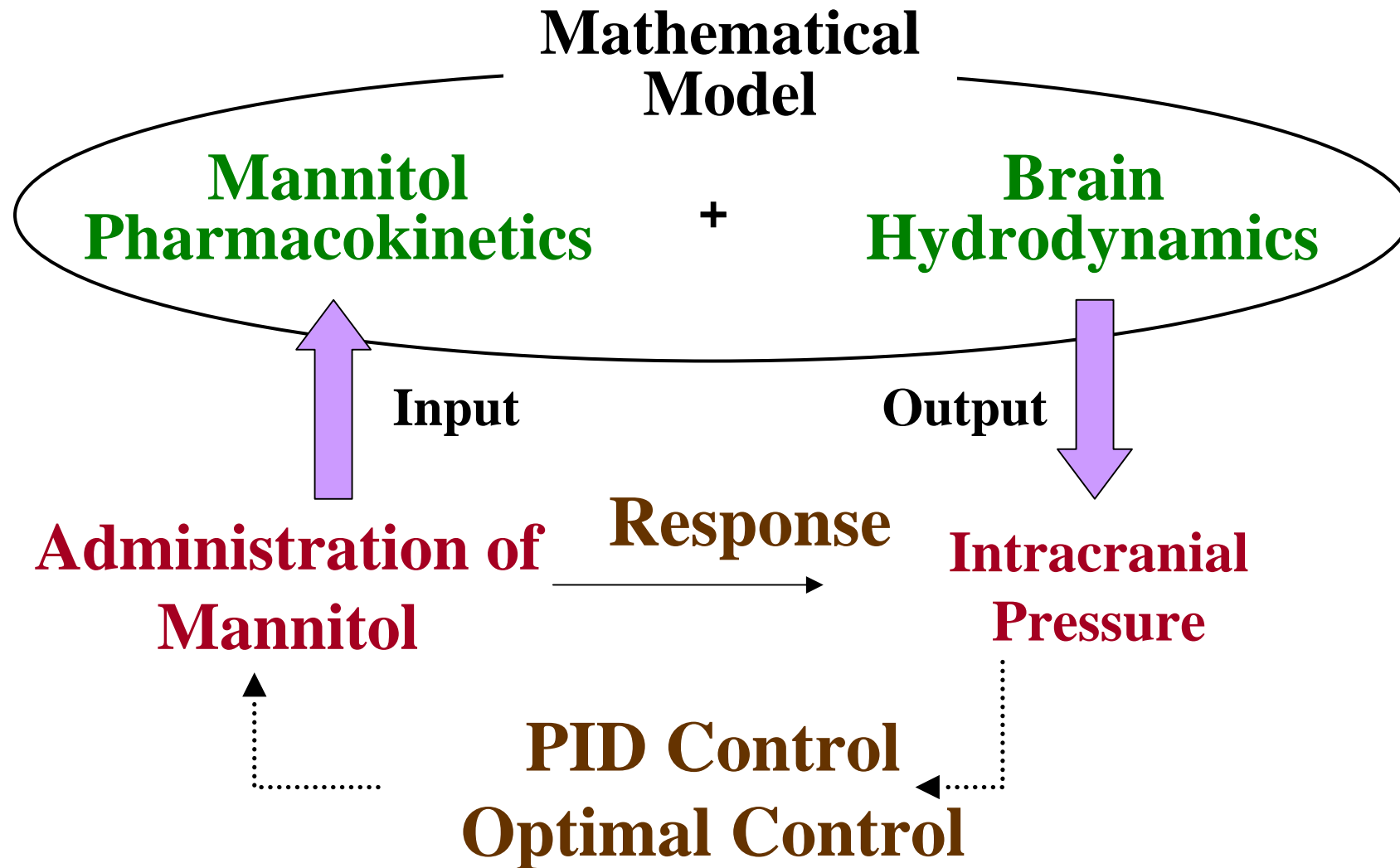
Iterative Administration based on experience of Doctors



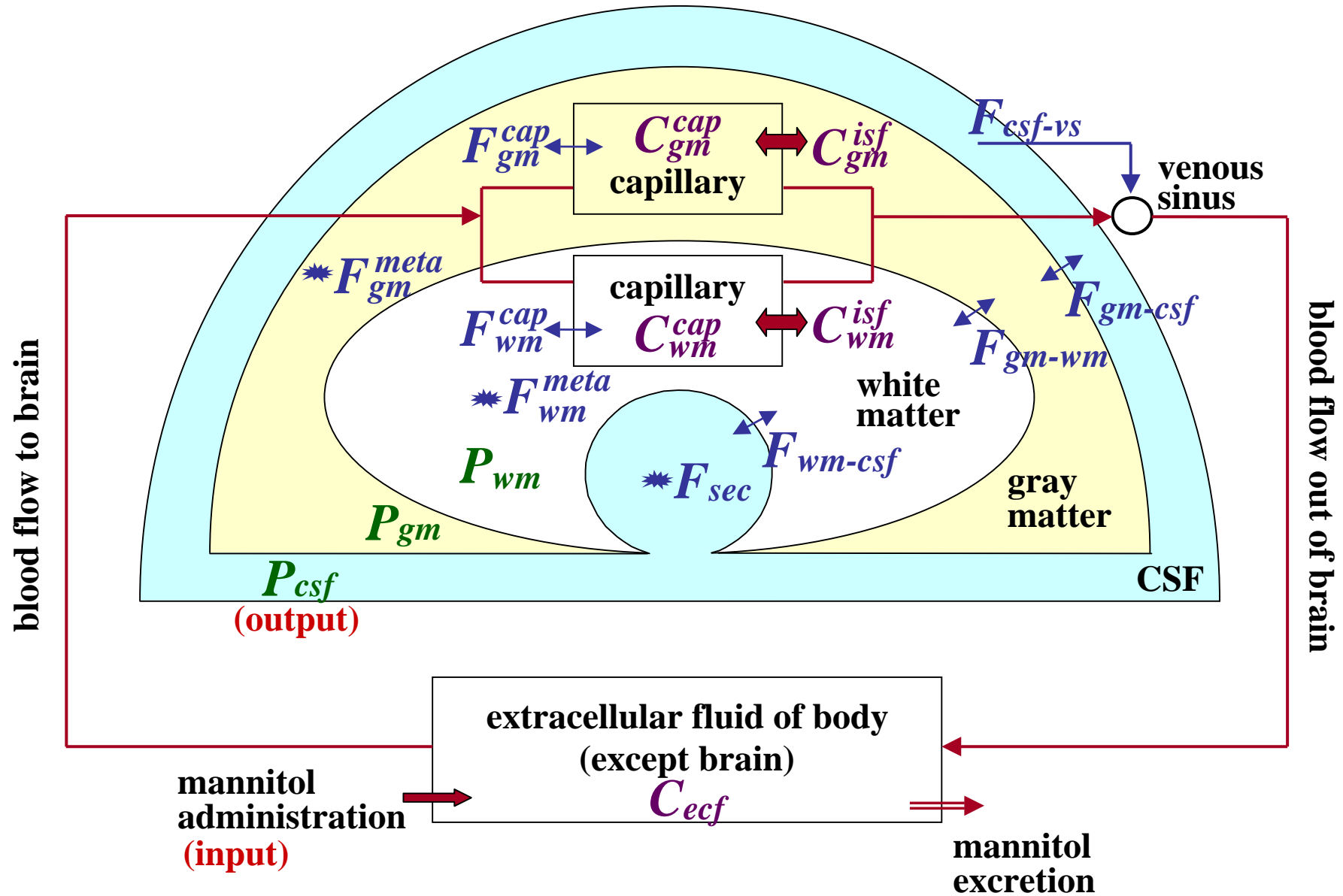
**Theoretical
analysis**

- **Determination of most effective administration process**
- **Dynamical Prediction of intracranial Pressure**

Method



Schematic Representation of Model



Pharmacokinetic Model of Mannitol

gray matter capillary

$$\frac{dC_{gm}^{cap}}{dt} = \frac{1}{V_{gm}^{cap}} [\underbrace{PS_{gm}}_{\text{permeation}} (C_{gm}^{isf} - C_{gm}^{cap}) + \underbrace{Q_{gm}}_{\text{blood flow}} (C_{ecf} - C_{gm}^{cap})]$$

white matter capillary

$$\frac{dC_{wm}^{cap}}{dt} = \frac{1}{V_{wm}^{cap}} [PS_{wm} (C_{wm}^{isf} - C_{wm}^{cap}) + Q_{wm} (C_{ecf} - C_{wm}^{cap})]$$

gray matter stroma

$$\frac{dC_{gm}^{isf}}{dt} = \frac{1}{V_{gm}^{isf}} [PS_{gm} (C_{gm}^{cap} - C_{gm}^{isf})]$$

white matter stroma

$$\frac{dC_{wm}^{isf}}{dt} = \frac{1}{V_{wm}^{isf}} [PS_{wm} (C_{wm}^{cap} - C_{wm}^{isf})]$$

ECF (except brain)

$$\frac{dC_{ecf}}{dt} = \frac{1}{V_{ecf}} (\underbrace{Q_{wm} C_{wm}^{cap}}_{\text{administration}} + Q_{gm} C_{gm}^{cap} - Q_{br} C_{ecf} - \underbrace{K_{cle} C_{ecf}}_{\text{excretion}} + I)$$

Hydraulic Model of Brain

gray matter

$$\frac{dP_{gm}}{dt} = K_{gm} (F_{gm}^{cap} + F_{gm}^{meta} - F_{gm-wm} - F_{gm-csf})$$



Based on Starling's Hypothesis

$$F_{gm}^{cap} = L_{cap} [(P_{cap} - P_{gm}) - \sum \sigma_i (\Pi_{cap}^i - \Pi_{gm}^i) - \sigma_{ma} RT (C_{gm}^{cap} - C_{gm}^{isf})]$$

CSF

$$\frac{dP_{csf}}{dt} = K_{csf} (F_{sec} + F_{wm-csf} + F_{gm-csf} - F_{csf-vs})$$

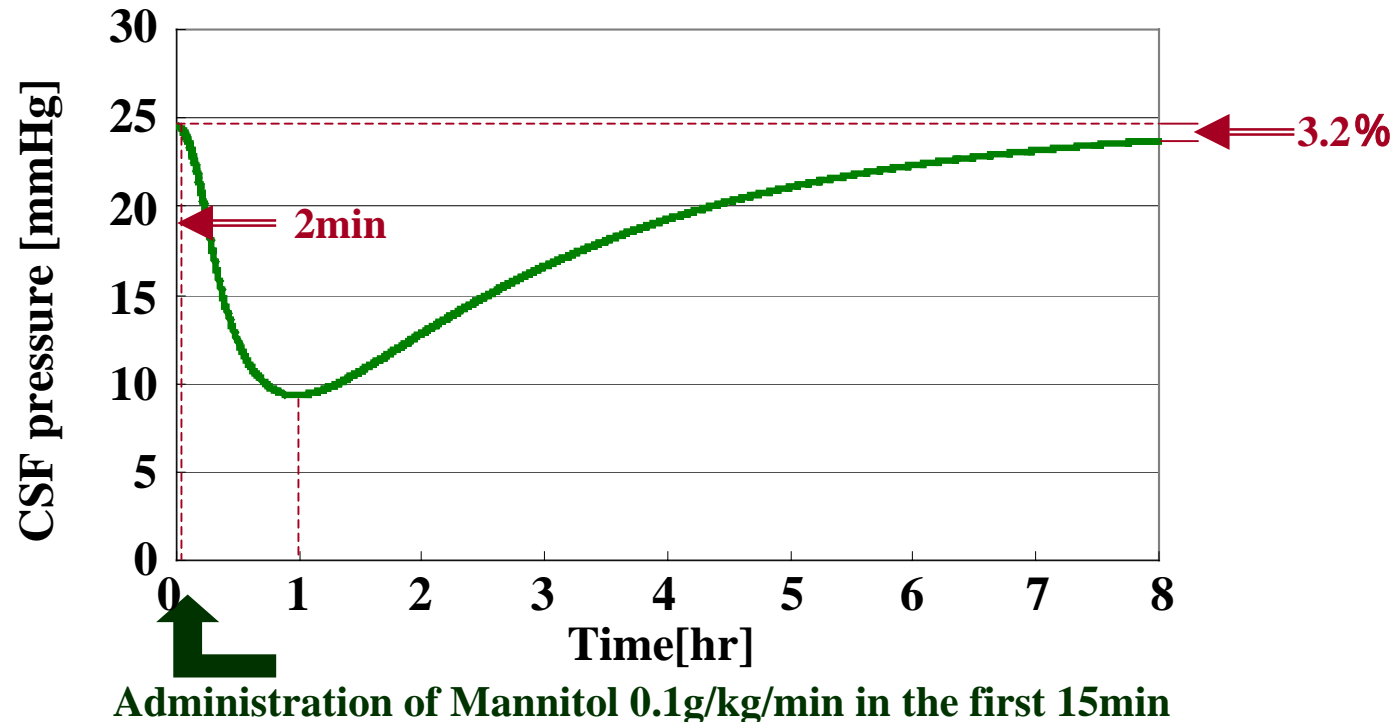
white matter

$$\frac{dP_{wm}}{dt} = K_{wm} (F_{wm}^{cap} + F_{wm}^{meta} + F_{gm-wm} - F_{wm-csf})$$

Due to Difference of Static Hydraulic Pressure

$$F_{gm-wm} = L_{gm-wm} (P_{gm} - P_{wm})$$

Dynamic Pressure in a Bolus Administration



Intracranial pressure quickly decreases in 2min and shows the minimum value in about 1hr after mannitol administration .

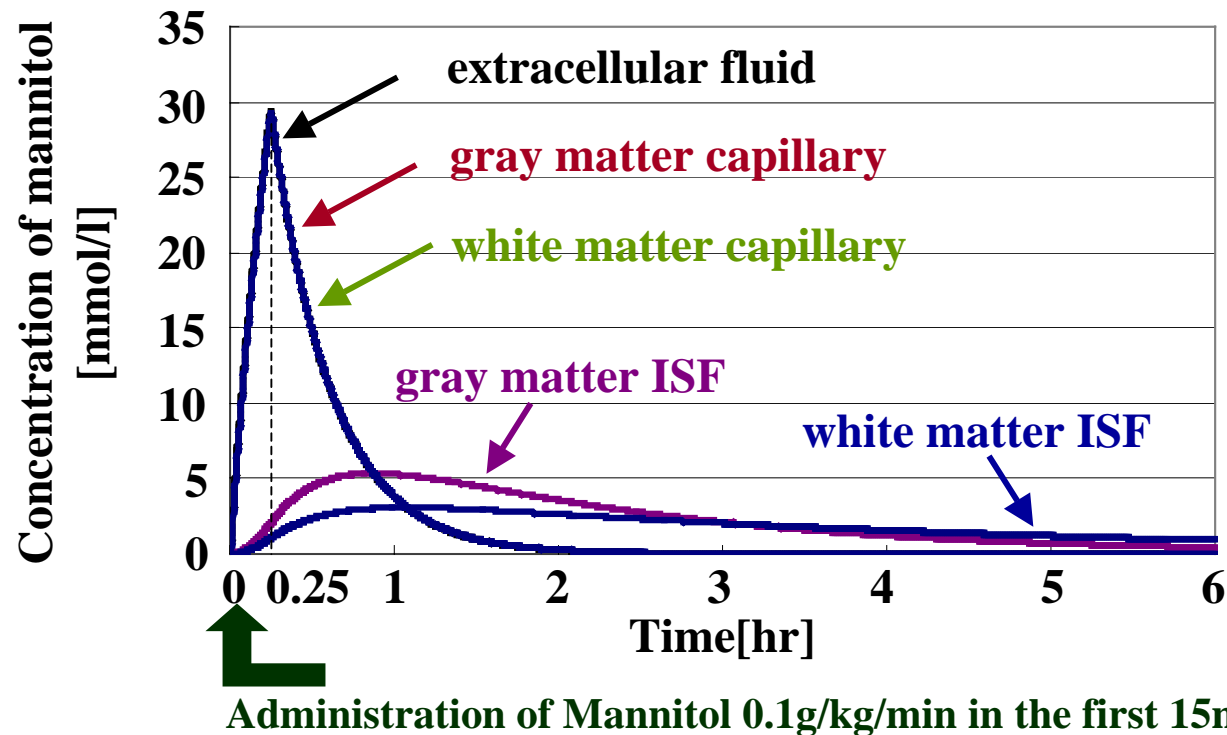
Then, it increases slowly and comes back to the 96.8% value of initial one in 8hr.



Consistent

1. “Reduction of cerebrospinal fluid pressure occurs within 15 minutes of the start of a mannitol infusion and lasts for 3 to 8 hours after the infusion is discontinued.” The extra pharmacopacia. 29th edition, 1989.
2. “By quick infusion to vein ICP decreases in 1-5 min and is expected to reach minimum in 20~60min”
救急医学(Critical Care Medicine) 25:1561-1564,2001.

Dynamics of Mannitol Concentration in a Bolus Administration



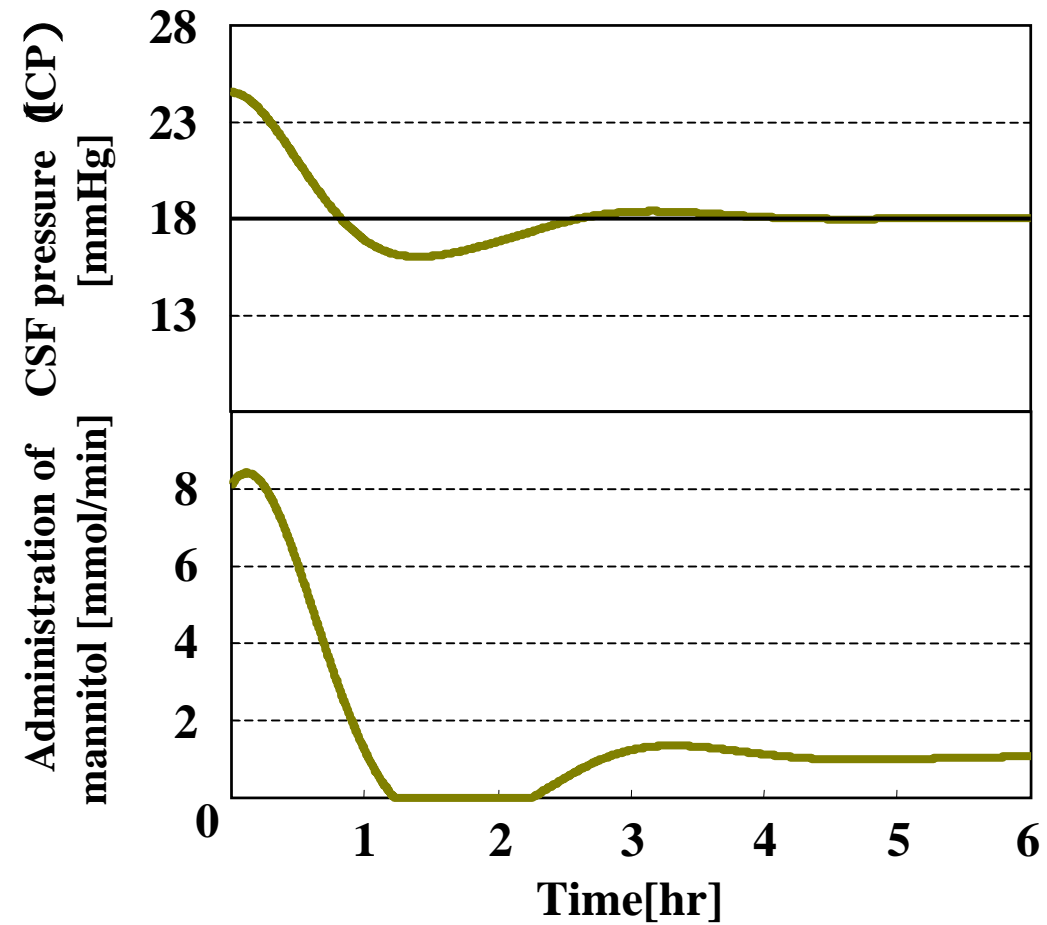
Mannitol concentration of extracellular fluid, gray matter capillary and white matter capillary. They decrease exponentially after their peak on the last moment of infusion.

↕ Consistent

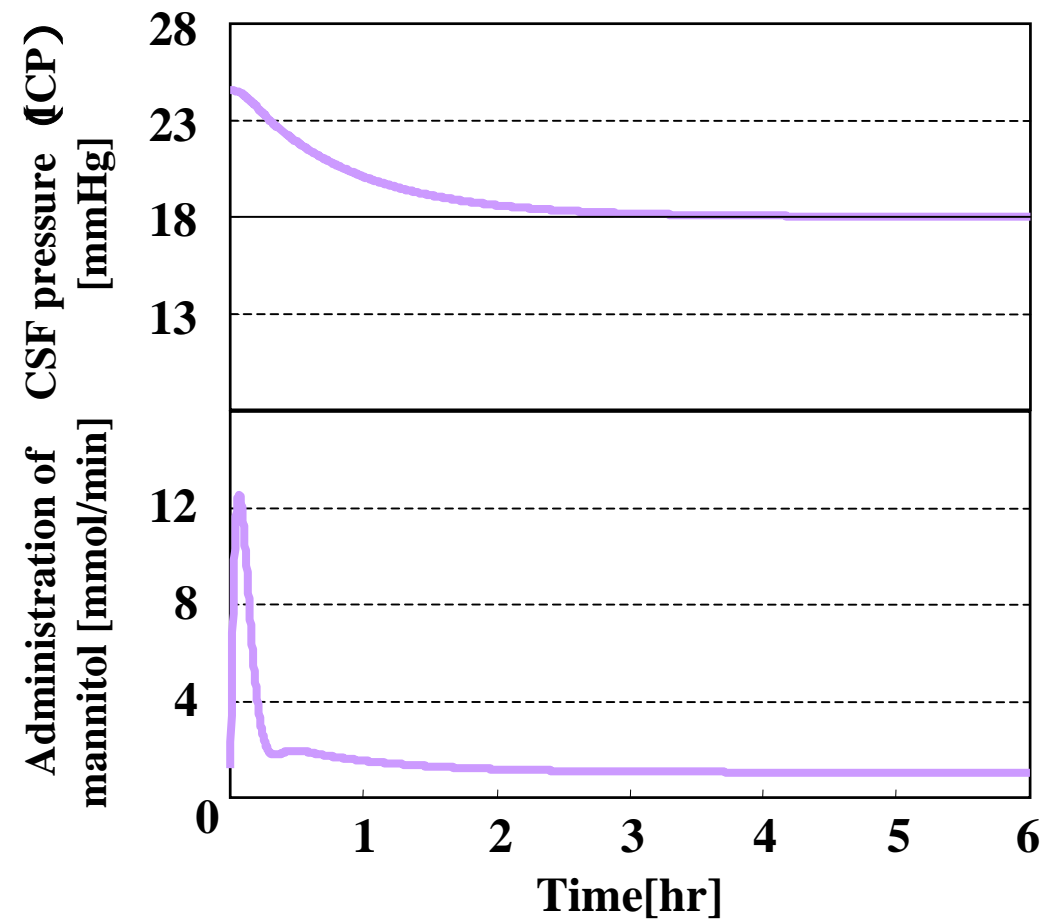
“Six human subjects received mannitol as an intravenous drip infusion. In each subject, the concentration of mannitol reached the maximum at the end of mannitol administration. Then, it exponentially decreased.”

Acta neurochir(suppl). 60: 538-540,1994.

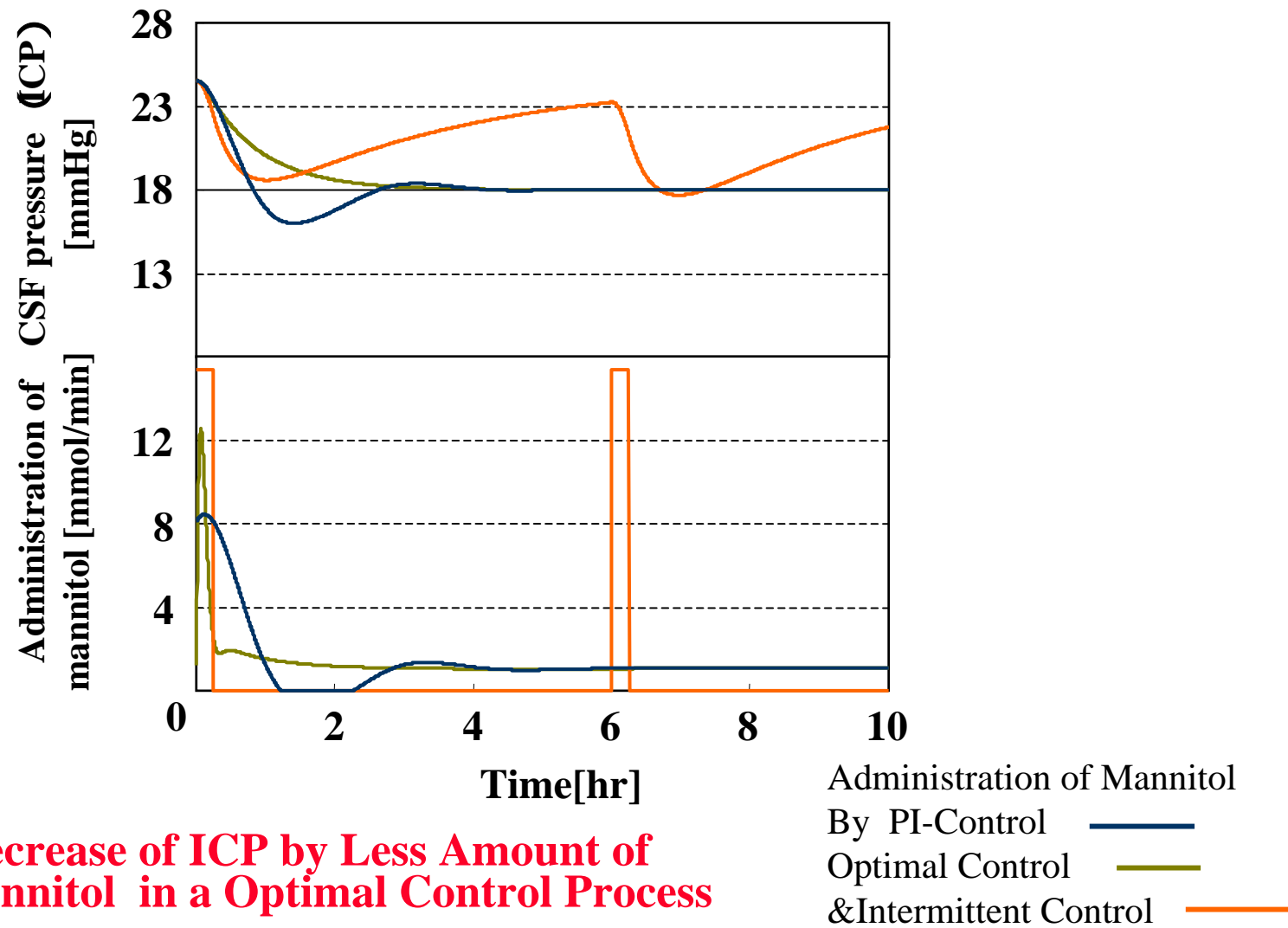
PI-Control of Pressure by Mannitol



Optimal Control of Pressure by Mannitol

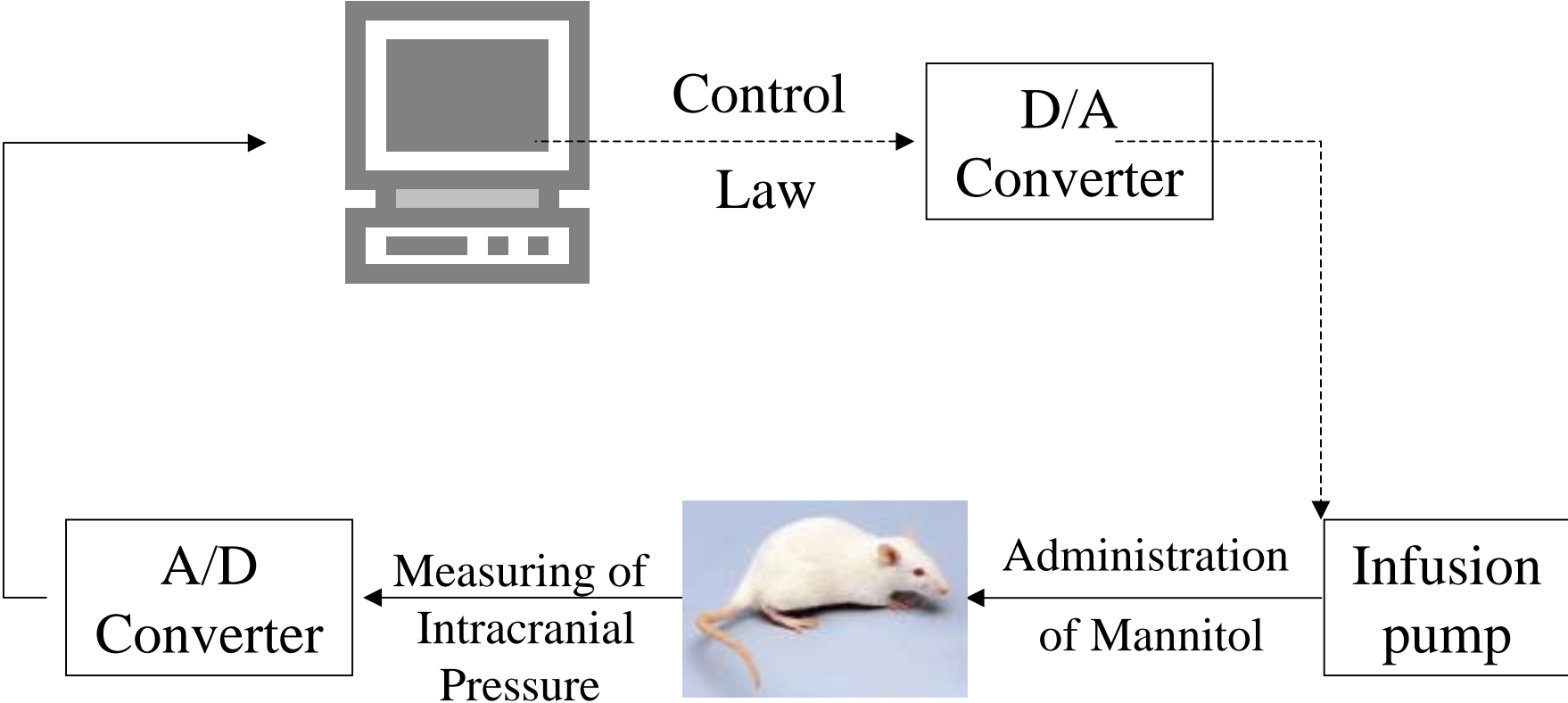


Comparison of Different Methods by Simulation



Animal Experiment

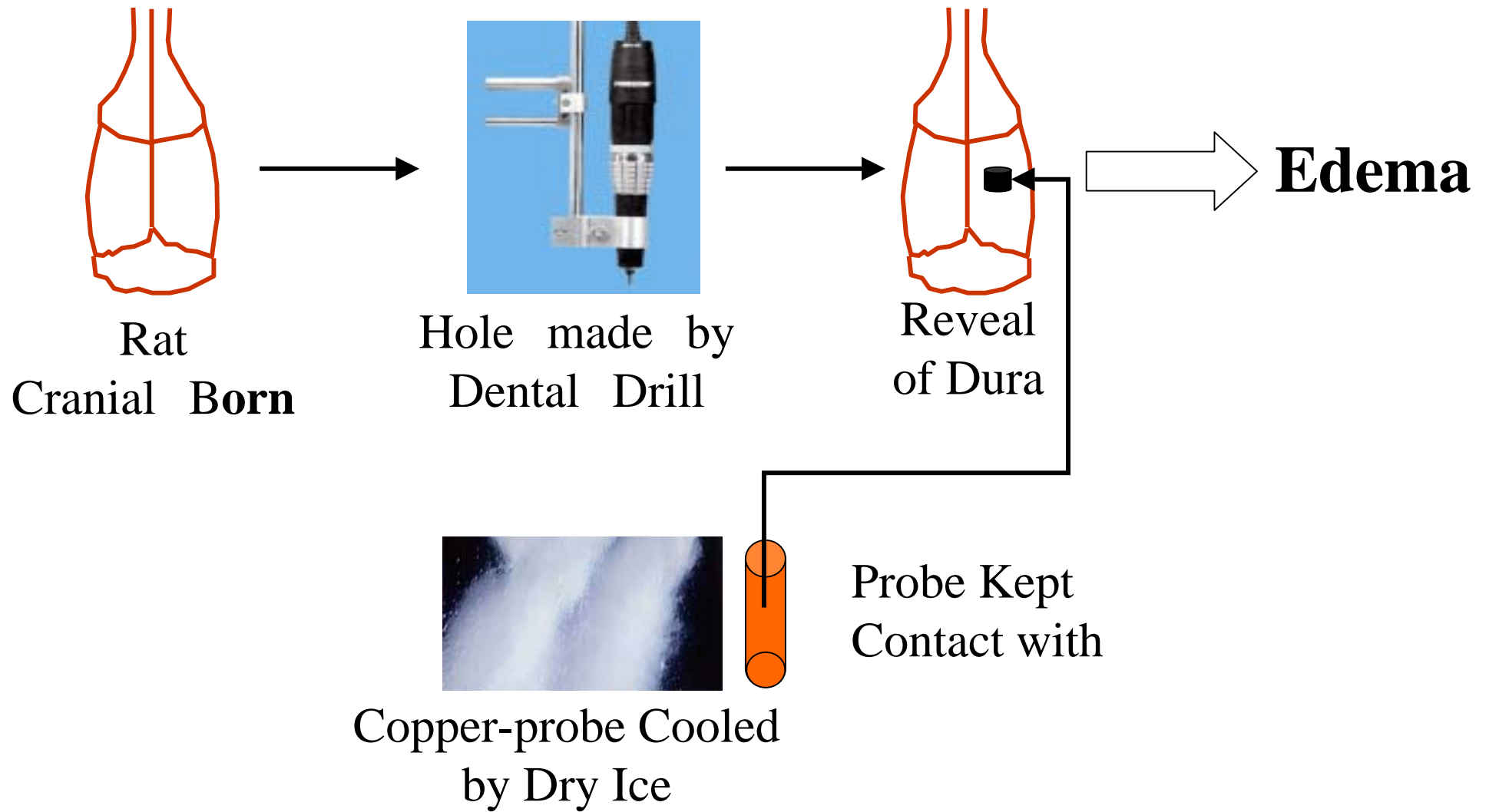
————— Response
----- Signal



Cold Lesion Edema

Control of Intracranial Pressure Using Rat

To Make the Cold Lesion Edema



On-line Monitoring of parallel Physiological Data

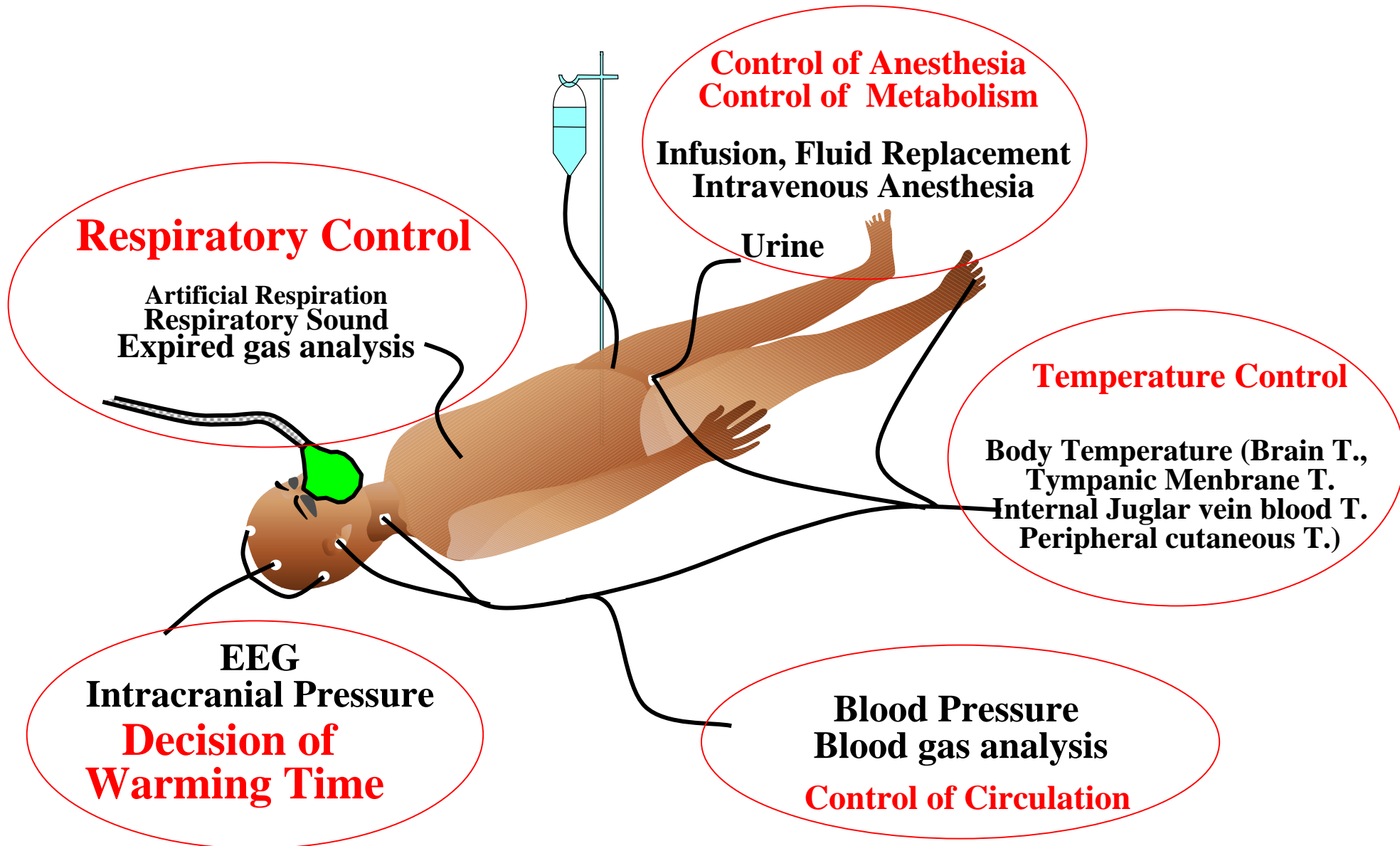
**Biophysical System Engineering
Graduate School of Allied Health Sciences
Tokyo Medical and Dental University**

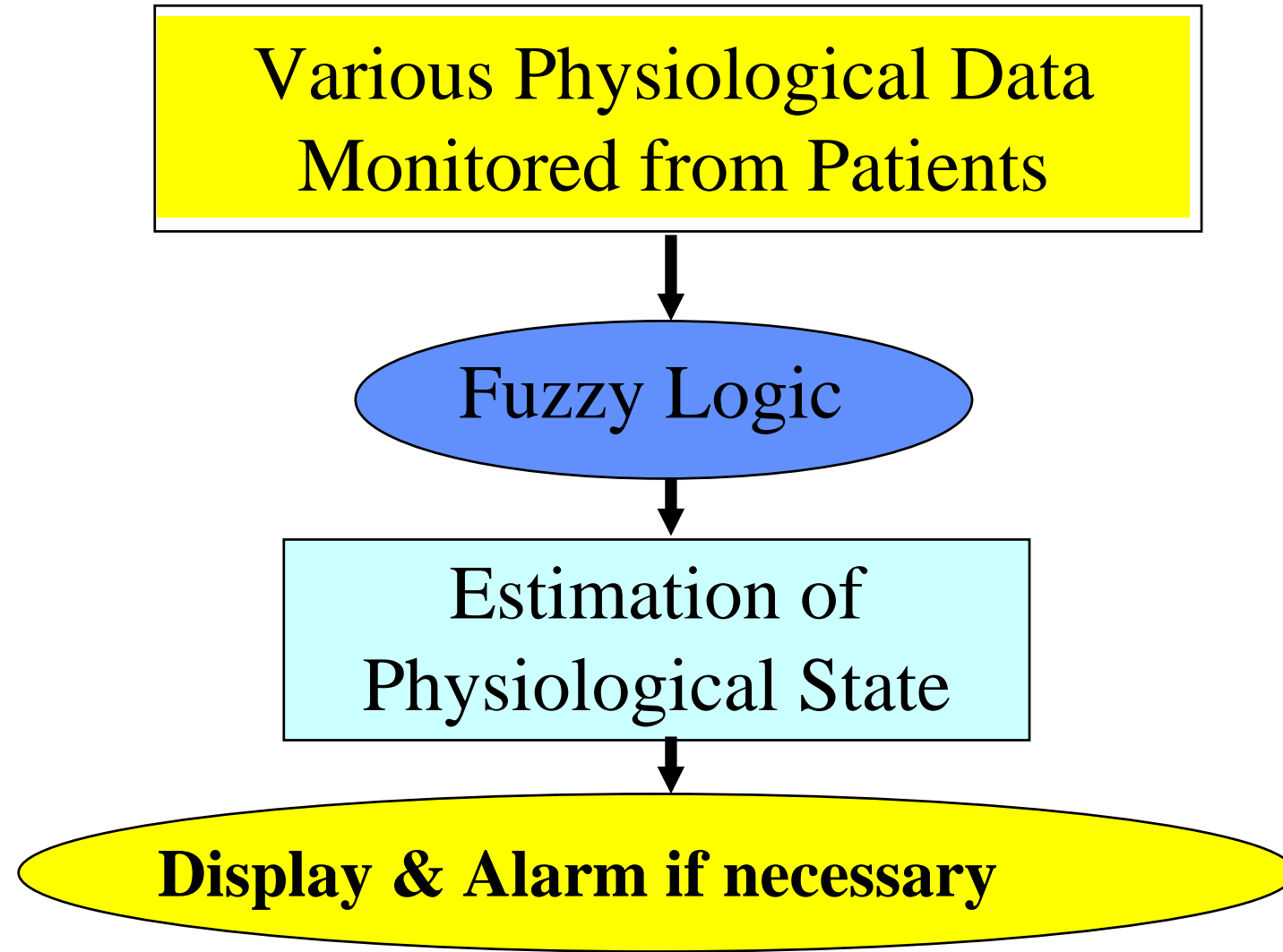
H.Wakamatsu, T.Utsuki, T.Wakatsuki



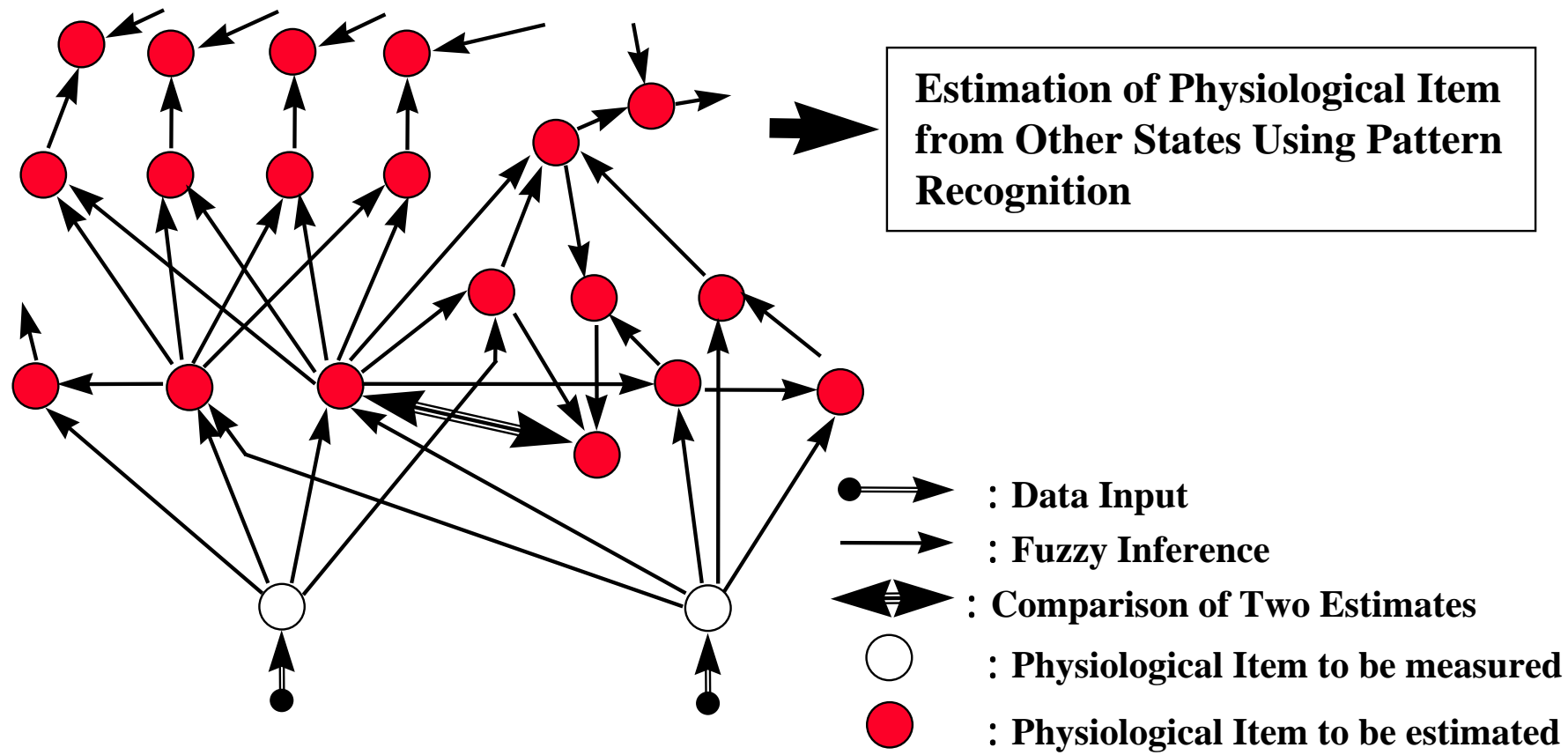
Monitoring System of Parallel Physiological Data

Conventional Monitoring of Physiological State





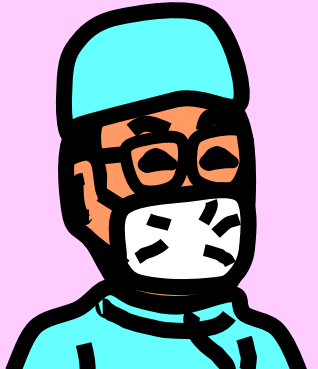
Evaluation and Alarming System



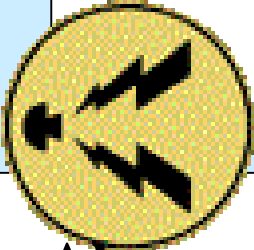
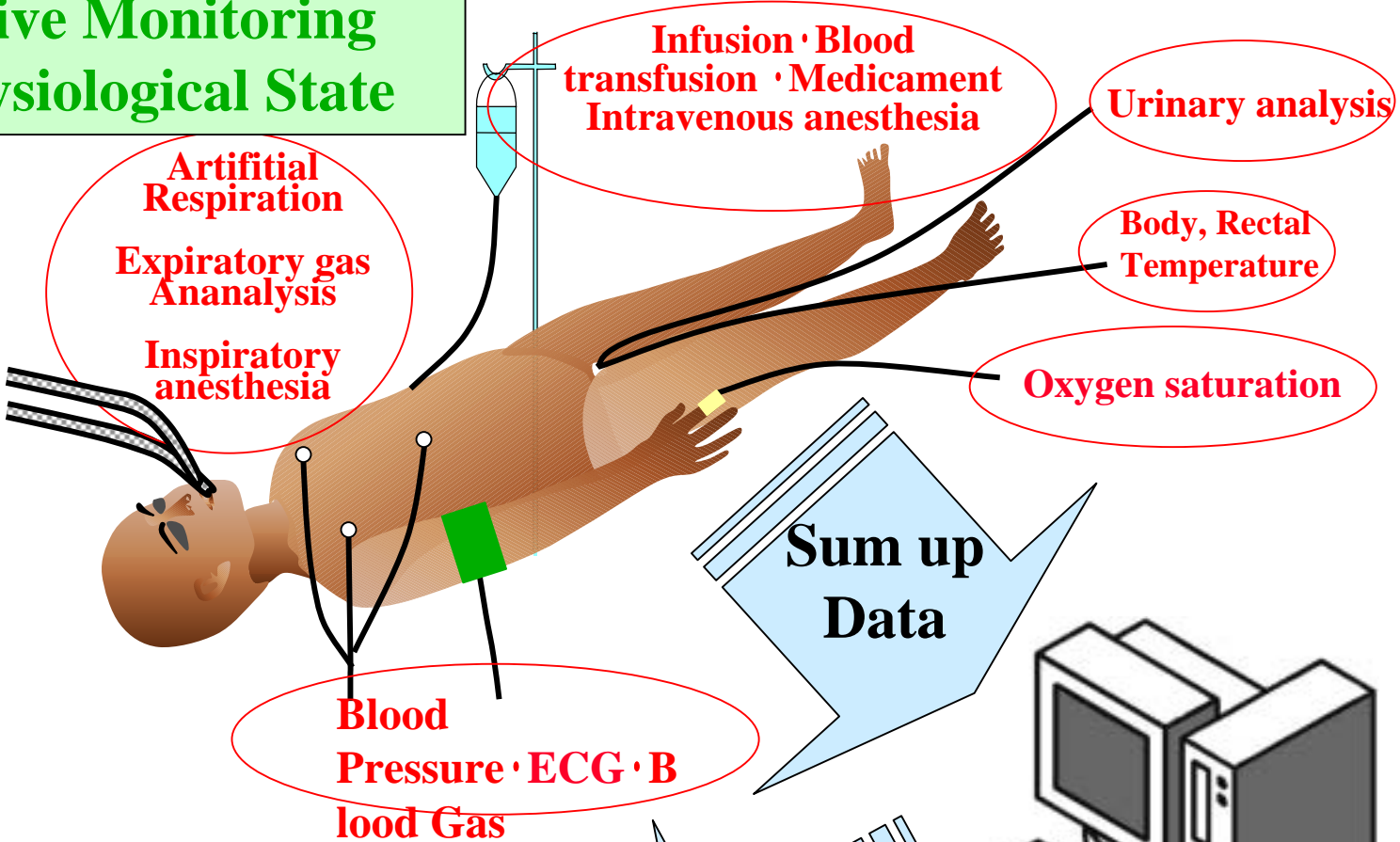
Estimation of Physiological Data by Fuzzy Inference Network

Comprehensive Monitoring System of Physiological State

Final Decision and Treatment



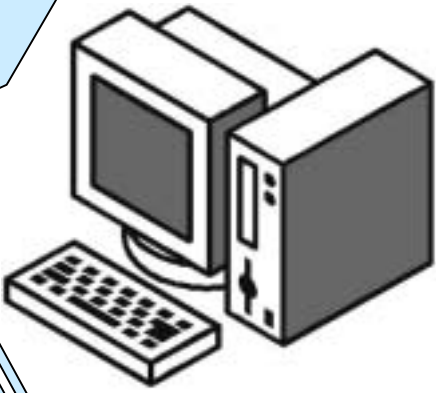
Anesthesiologist



Alarm

Indication by Simple Expression

Sum up Data



Physiological State

Inference, Decision & Description